

$$\int_0^t g(s, W_s) dW_s \stackrel{\Delta}{=} \lim_{\| \tau \| \rightarrow 0} \sum_k g(t_{k+1}, W_{t_{k+1}}) \Delta W_k$$

\uparrow

$(W_{t_k} - W_{t_{k-1}})$

$$\Pi = \{ t_0, t_1, \dots, t_n \}$$

$$0 = t_0 < t_1 < \dots < t_n = t$$

Ito's Lemma I:

If $X_t = h(W_t)$, and $h(y)$ is twice diff.

then $dX_t = h'(W_t) dW_t + \frac{1}{2} h''(W_t) dt$ ←
Ito correction

stochastic differential equation

$$(X_t - X_0 = \int_0^t h'(W_s) dW_s + \frac{1}{2} \int_0^t h''(W_s) ds)$$

e.g. $X_t = W_t^2$, $h(y) = y^2$

$$dX_t = 2W_t dW_t + \frac{1}{2} \cdot 2 \cdot dt$$

$$= 2W_t dW_t + dt$$

$$X_t - X_0 = 2 \underbrace{\int_0^t W_s dW_s}_{\text{Ito correction.}} + \int_0^t dt$$

$$\Rightarrow \int_0^t W_s dW_s = \frac{1}{2} [(W_t^2 - W_0^2) - t]$$

$$= \frac{1}{2} [W_t^2 - t]$$

↑ Ito correction.

+ .

e.g., int. by parts for $\int_0^t W_s^4 dW_s$

natural $X_t = W_t^5$, $h(y) = y^5$
to consider

$$dX_t = 5 W_t^4 \cdot dW_t + \frac{1}{2} \cdot 5 \cdot 4 \cdot W_t^3 dt$$
$$h'(W_t) dW_t + \frac{1}{2} h''(W_t) dt$$

$$\Rightarrow \int_0^t W_s^4 dW_s = \frac{1}{5} \left[W_t^5 - 10 \int_0^t W_s^3 ds \right]$$

Suppose that S_t satisfies the SDE:

$$dS_t = \sigma S_t dW_t$$

What is the solution this SDE?

reminder: solve the ODE:

$$dz_t = \sigma z_t dg_t$$

$$z_t = (\sigma, g, s, g', \dots)$$

$$\frac{dz_t}{z_t} = \sigma dg_t$$

$$\underline{d(\ln z_t)} = \underline{\frac{dz_t}{z_t}} = \underline{\sigma dg_t}$$

$$\Rightarrow \ln z_t - \ln z_0 = \sigma (g_t - g_0)$$

$$\Rightarrow z_t = z_0 e^{\sigma (g_t - g_0)}$$

$$\frac{dS_t}{S_t} = \sigma dW_t \iff dS_t = \sigma S_t dW_t$$

$$d\ln S_t \neq \sigma dW_t$$

$$h(S_t) \text{ where } h(y) = \ln y$$

Ito's Lemma II:

$$\text{suppose } dY_t = \sigma(t, Y_t) dW_t \text{ and}$$

$$X_t = h(Y_t) \text{ with } h(y) \text{ being twice diff, then}$$

$$dX_t = h'(Y_t) \underbrace{dY_t}_{\sigma(t, Y_t) dW_t} + \underbrace{\frac{1}{2} h''(Y_t) \cdot \sigma^2(t, Y_t) dt}_{\text{Ito correction.}}$$

$$X_t = h(W_t)$$

$$dX_t = h'(W_t) dW_t + \frac{1}{2} h''(W_t) dt$$

$$\text{so } X_t = \ln S_t, \quad h(y) = \ln y$$

$$dX_t = \left(\frac{1}{S_t}\right) dS_t + \frac{1}{2} \left(-\frac{1}{S_t^2}\right) \cdot (\sigma S_t)^2 dt$$

$$= \sigma dW_t - \underbrace{\frac{1}{2} \sigma^2 dt}_{\text{Ito correction}}$$

$$\Rightarrow X_t - X_0 = \sigma (W_t - W_0) - \frac{1}{2} \sigma^2 t$$

$$\Rightarrow X_t = X_0 + \sigma (W_t - W_0) - \frac{1}{2} \sigma^2 t$$

$$\Rightarrow d\ln S_t = \ln S_0 + \sigma (W_t - W_0) - \frac{1}{2} \sigma^2 t$$

$$S_t = S_0 e^{\sigma (W_t - W_0) - \frac{1}{2} \sigma^2 t} \Leftrightarrow dS_t = \sigma S_t dW_t$$

$$Z_t = Z_0 e^{\sigma (g_t - g_0)} \Leftrightarrow dZ_t = \sigma Z_t dg_t$$

$$\frac{dS_t}{S_t} = \sigma dW_t$$

↗ ↘

instantaneous return of S_t

source of noise
size of fluctuations
(volatility)

drift or expected instantaneous return

$$\frac{dS_t}{S_t} = \mu dt + \sigma dW_t$$

Ito Lemma's:

suppose that Y_t satisfies the SDE

$$dY_t = u(t, Y_t) dt + \sigma(t, Y_t) dW_t$$

and $X_t = h(t, Y_t)$ which is once diff in t
+ twice " " y

then:

$$dX_t = \underbrace{\partial_y h(t, Y_t) dY_t}_{\text{Ito correction}} + \partial_t h(t, Y_t) dt + \underbrace{\frac{1}{2} \partial_{yy} h(t, Y_t) \sigma^2(t, Y_t) dt}_{\text{Ito correction}}$$

(note for B. with $\mu=0, \sigma=1$)

e.g. find an integration by parts formula for:

$$\int_s^t S_w dW_s$$

$\hookrightarrow \partial_y h(t, w_t) \text{ so choose } h(t, y) = t y^2$
 $x_t = h(t, w_t)$

$$\text{so } dx_t = 2t w_t \cdot dw_t + w_t^2 dt \\ + \frac{1}{2} 2t \cdot dt$$

$$\Rightarrow t w_t dw_t = \frac{1}{2} [dx_t - (w_t^2 - t) dt]$$

$$\Rightarrow \int_0^t s w_s dw_s = \frac{1}{2} \left[x_t - x_0 - \int_0^t (w_s^2 - s) ds \right] \\ = \frac{1}{2} \left[t w_t^2 - \int_0^t (w_s^2 - s) ds \right]$$

Find an integration by parts formula for

$$\int_0^t s^2 w_s^3 dw_s.$$

suppose that y_t satisfies the SDE

$$dy_t = \mu(t, y_t) dt + \sigma(t, y_t) dW_t \quad \leftarrow$$

and $X_t = h(t, y_t)$ which is once diff in t
+ twice " " y

then:

$$\begin{aligned} dX_t &= \underbrace{\partial_y h(t, y_t)}_{dY_t} + \partial_t h(t, y_t) dt \\ &\quad + \frac{1}{2} \partial_{yy} h(t, y_t) \sigma^2(t, y_t) dt \end{aligned}$$

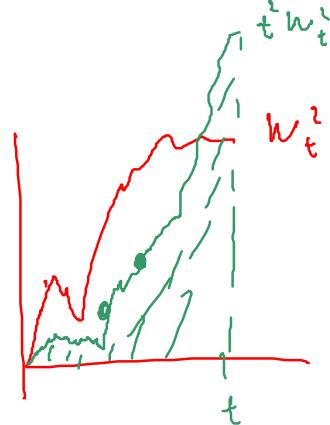
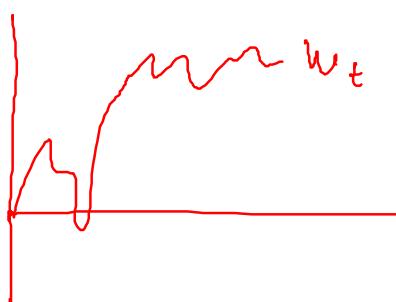
find an integration by parts formula for $\int_0^t s^2 W_s^3 dW_s$

$$h(t, y) = t^2 y^4, \quad X_t = h(t, W_t)$$

$$dX_t = \underbrace{4 t^2 W_t^3 dW_t}_{\text{in}} + (2t W_t^4 + \frac{1}{2} 4 \cdot 3 \cdot t^2 \cdot W_t^2) dt$$

$$\int_0^t s^2 W_s^3 dW_s = \frac{1}{4} \left[t^2 W_t^4 - \int_0^t (2s W_s^4 + 6s^2 W_s^2) ds \right]$$

$$\int_0^t s^2 W_s^2 ds$$



Geometric Brownian motion (GBM)

$$ds_t = \mu s_t dt + \sigma s_t dW_t \quad (\text{Black-Scholes model})$$

$$\frac{ds_t}{s_t} = \mu dt + \sigma dW_t$$

$$X_t = \ln s_t \quad h(y) = \ln y$$

$$dx_t = \left(\frac{1}{s_t} \right) ds_t + 0 dt + \frac{1}{2} \left(-\frac{1}{s_t^2} \right) \cdot (\sigma s_t)^2 dW_t$$

$\hookrightarrow \partial_y h(s_t)$ $\hookrightarrow \partial_{tt} h(s_t) = 0$ $\hookrightarrow \partial_{yy} h(s_t)$
 $\partial_t h(s_t) \neq h'(s_t) \partial_t s_t$

$$h: \mathbb{R}_+ \times \mathbb{R} \mapsto \mathbb{R}$$

$$(t, y) \mapsto h(t, y)$$

$$\partial_t h(t, s_t) = \left. \partial_t h(t, y) \right|_{y=s_t}$$

$$= \left(\frac{1}{s_t} \right) (\mu s_t dt + \sigma s_t dW_t) - \frac{1}{2} \sigma^2 dW_t$$

$$\Rightarrow dx_t = (\mu - \frac{1}{2} \sigma^2) dt + \sigma dW_t$$

$$x_t - x_0 = (\mu - \frac{1}{2} \sigma^2) t + \sigma W_t$$

$$s_t = s_0 e^{(\mu - \frac{1}{2} \sigma^2)t + \sigma W_t}$$

$$\text{solves } ds_t = \mu s_t dt + \sigma s_t dW_t$$

$$s_T = s_0 e^{(\mu - \frac{1}{2} \sigma^2)T + \sigma W_T}$$

$$\stackrel{d}{=} s_0 e^{(\mu - \frac{1}{2} \sigma^2)T + \sigma \sqrt{T} Z}$$

$$Z \sim N(0, 1)$$

$$\begin{aligned}\mathbb{E}[S_T] &= S_0 e^{(\mu - \frac{1}{2}\sigma^2)T} + \mathbb{E}[e^{\sigma\sqrt{T}Z}] \\ &= S_0 e^{(\mu - \frac{1}{2}\sigma^2)T} e^{\frac{1}{2}\sigma^2 T} \\ &= S_0 e^{\mu T}\end{aligned}$$

given: $S_t = S_0 e^{(\mu - \frac{1}{2}\sigma^2)t + \sigma W_t}$ find the SDE for S_t

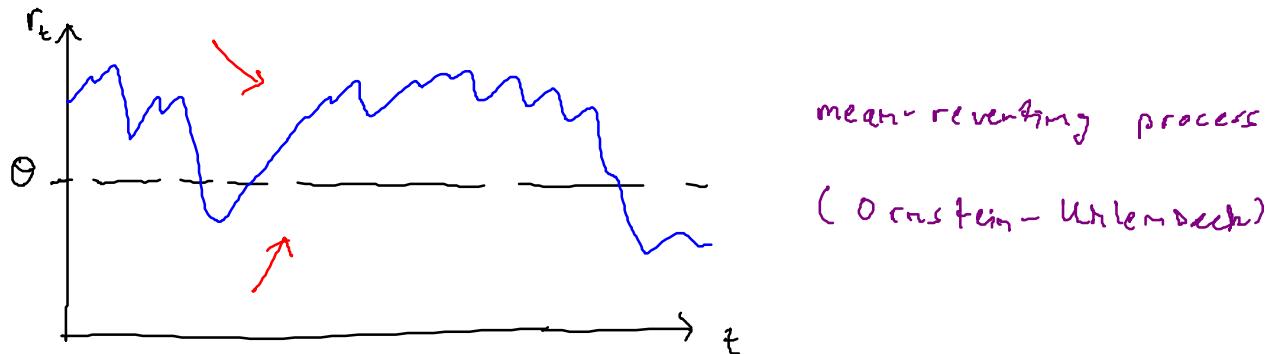
$$S_t = h(t, W_t), \quad h(t, y) = S_0 e^{(\mu - \frac{1}{2}\sigma^2)t + \sigma y}$$

$$\begin{aligned}dS_t &= \partial_y h(t, W_t) \cdot dW_t + \partial_t h(t, W_t) dt \\ &\quad + \frac{1}{2} \partial_{yy} h(t, W_t) dt \\ &= \sigma S_t dW_t + (\mu - \frac{1}{2}\sigma^2) S_t dt \\ &\quad + \frac{1}{2} \sigma^2 S_t dt \\ &= \mu S_t dt + \sigma S_t dW_t\end{aligned}$$

$$\kappa, \theta, \sigma > 0.$$

Vasicek Model:

$$r_t - r_{t-1} = \underbrace{\kappa(\theta - r_{t-1})}_{\text{mean-reverting}} \Delta t + \sigma \sqrt{\Delta t} \varepsilon_t$$



$$dr_t = \kappa(\theta - r_t) dt + \sigma dW_t$$

$$\begin{aligned} \sigma = 0 : \quad dr_t &= -\kappa r_t dt \\ \theta = 0 : \quad r_t &= r_0 e^{-\kappa t} \end{aligned}$$

$$\rightarrow \text{try } r_t = e^{-\kappa t} g_t = h(t, g_t), \quad h(t, y) = e^{-\kappa t} y$$

$$g_t = e^{\kappa t} r_t = h(t, r_t), \quad h(t, y) = e^{\kappa t} y$$

$$\begin{aligned} dg_t &= \partial_y h(t, r_t) dr_t + \partial_t h(t, r_t) dt \\ &\quad + \frac{1}{2} \partial_{yy} h(t, r_t) \sigma^2 dt \end{aligned}$$

$$\begin{aligned} &= e^{\kappa t} \left(\kappa(\theta - r_t) dt + \sigma dW_t \right) \\ &\quad + \kappa e^{\kappa t} r_t dt \\ &\quad + \frac{1}{2} \sigma^2 dt \end{aligned}$$

$$\Rightarrow dg_t = \kappa \theta e^{\kappa t} dt + e^{\kappa t} \sigma dW_t$$

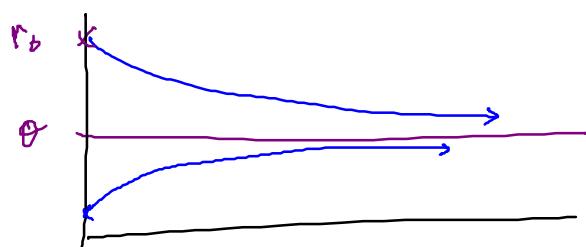
$$g_t - g_0 = \kappa \theta \int_0^t e^{\kappa s} ds + \sigma \int_0^t e^{\kappa s} dW_s$$

$$\Rightarrow e^{\kappa t} r_t - r_0 = \kappa \theta \frac{e^{\kappa t} - 1}{\kappa} + \sigma \int_0^t e^{\kappa s} dW_s$$

\Rightarrow

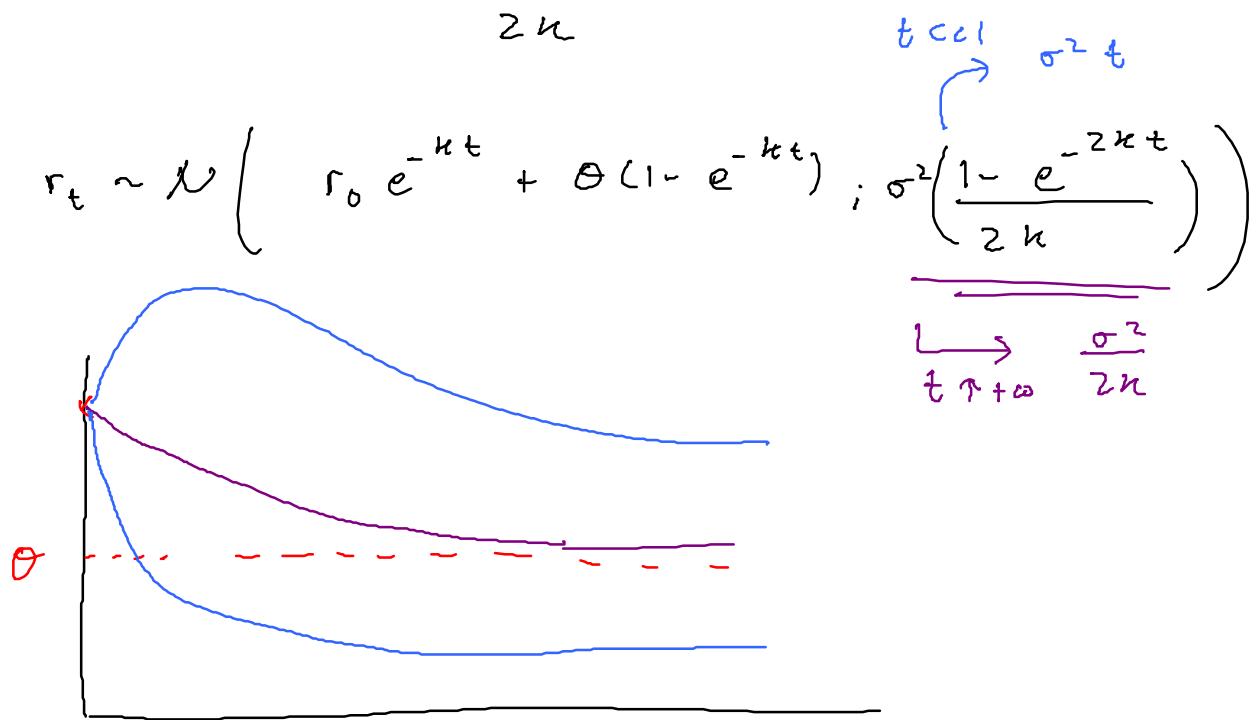
$$r_t = r_0 e^{-\kappa t} + \theta(1 - e^{-\kappa t})$$

$$+ \sigma \int_0^t e^{-\kappa(t-s)} dW_s$$



$$\text{now } \int_0^t e^{-\kappa(t-s)} dW_s \sim N(m, v)$$

$$\begin{aligned} \text{IE} \left[\int_0^t e^{-\kappa(t-s)} dW_s \right] &= 0 \\ \text{V} \left[\int_0^t e^{-\kappa(t-s)} dW_s \right] &= \text{IE} \left[\left(\int_0^t e^{-\kappa(t-s)} dW_s \right)^2 \right] \\ &= \text{IE} \left[\int_0^t e^{-2\kappa(t-s)} ds \right] \\ &= \int_0^t e^{-2\kappa(t-s)} ds \\ &= \underline{1 - e^{-2\kappa t}} \end{aligned}$$



$$dr_t = \kappa(\theta - r_t) dt + \sigma dW_t$$

$$\underbrace{r_{t_n} - r_{t_{n+1}}}_{\Delta r} \stackrel{d}{=} \kappa(\theta - r_{t_{n+1}}) \Delta t + \sigma \sqrt{\Delta t} Z$$

$$\kappa \theta \Delta t + (1 - \kappa \Delta t) r_{t_n} + \sigma \sqrt{\Delta t} Z$$

Itô's isometry:

$$\begin{aligned} & \mathbb{E} \left[\left(\int_0^t g(s, w_s) dW_s \right)^2 \right] \\ &= \mathbb{E} \left[\int_0^t (g(s, w_s))^2 ds \right] \end{aligned}$$

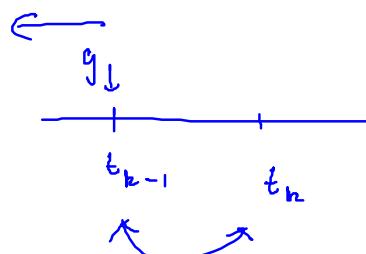
Suppose $w_t + B_t$ are corr. B. with corr = p.

$$\begin{aligned} & \mathbb{E} \left[\left(\int_0^t g(s, w_s, B_s) dW_s \right) \left(\int_0^t h(s, w_s, B_s) dB_s \right) \right] \\ &= \mathbb{E} \left[\int_0^t g(s, w_s, B_s) h(s, w_s, B_s) p ds \right] \end{aligned}$$

$$\mathbb{E} \left[\int_0^t g(s, w_s, B_s) dw_s \right] = 0$$

tube a partition Π

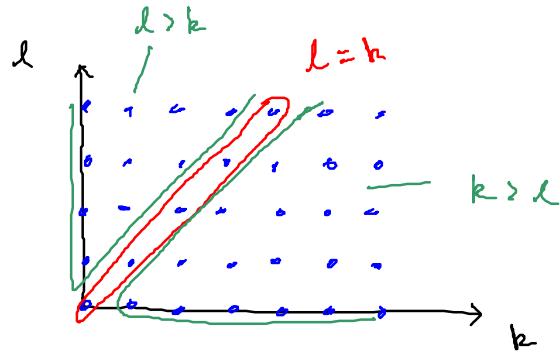
$$\begin{aligned} & \mathbb{E} \left[\sum_k g_{t_{k-1}} \Delta W_k \right] \\ &= \sum_k \mathbb{E} [g_{t_{k-1}} \Delta W_k] \end{aligned}$$



$$= \sum_k \mathbb{E} [g_{t_{k-1}}] \mathbb{E} [\Delta W_k] = 0$$

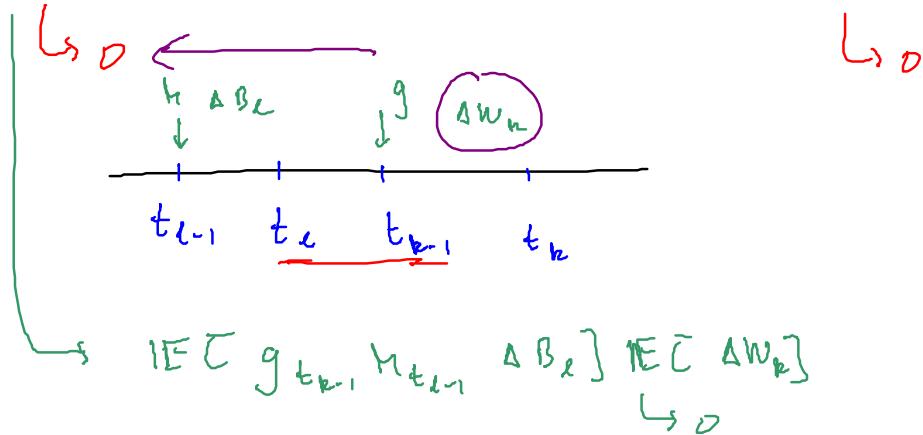
for Itô's isometry tube a partition Π
for Sotn integrals:

$$I = \mathbb{E} \left[\sum_k g_{t_{k-1}} \underline{\Delta W_k} \quad \sum_l h_{t_{k-1}} \underline{\Delta B_l} \right]$$



$$\sum_h \mathbb{E} [g_{t_{k-1}} h_{t_{k-1}} \Delta W_h \Delta B_k]$$

$$+ \sum_{h>k} \mathbb{E} [g_{t_{k-1}} h_{t_{k-1}} \Delta W_k \Delta B_h] + C \quad (l \leftrightarrow h)$$



$$\mathbb{E} [g_{t_{k-1}} h_{t_{k-1}} \Delta W_{t_k} \Delta B_{t_k}]$$

$$= \mathbb{E} [g_{t_{k-1}} h_{t_{k-1}}] \mathbb{E} [\Delta W_{t_k} \Delta B_{t_k}]$$

$\downarrow g \Delta t_n$

$$\therefore I'' = \sum_k \mathbb{E} [g_{t_{k-1}} h_{t_{k-1}}] p \Delta t_n$$

$$= \mathbb{E} \left[\sum_k g_{t_{k-1}} h_{t_{k-1}} p \Delta t_n \right]$$

$$\lim_{\|\pi\| \downarrow 0} I^\pi = \mathbb{E} \left[\lim_{n \rightarrow \infty} \sum_k g_{t_{k-1}} h_{t_{k-1}} \beta^{d_{t_k}} \right]$$

$$= \mathbb{E} \left[\int_0^t g(s, w_s, B_s) h(s, w_s, B_s) \beta ds \right]$$