

- ① Feynman-Hellmann & Girsanov's Thm
- ② IR model
- ③ numerical measures

Feynman-Kac Theorem

$$f(t, s) = \mathbb{E}^Q \left[e^{-\int_t^T r(u, S_u) du} \Phi(S_T) \mid S_t = s \right]$$

$$\frac{dS_t}{S_t} = \mu(t, S_t) dt + \sigma(t, S_t) d\hat{W}_t$$

L Q-B.m.m.

then f is the unique sol of

$$\begin{cases} \partial_t f + \mu(t, s) s \partial_s f + \frac{1}{2} \sigma^2(t, s) s^2 \partial_{ss} f = r(t, s) f \\ f(T, s) = \Phi(s) \end{cases}$$

recall that if X_t is our underlying risk

$$\bullet \quad dX_t = \mu^x(t, X_t) dt + \sigma^x(t, X_t) dW_t$$

L P-B.m.m.

$$\bullet \quad \frac{dM_t}{M_t} = r(t, X_t) dt \quad \text{traded}$$

$$\bullet \quad \frac{df_t}{f_t} = \mu^f(t, X_t) dt + \sigma^f(t, X_t) dW_t \quad \text{traded}$$

then dynamic hedging argument $\Rightarrow$ value of a claim $g_t = g(t, X_t)$ s.t. $g_T = \Phi(X_T)$ satisfies:

$$\begin{cases} \partial_t g + (\mu^x - \sigma^x \lambda) \partial_x g + \frac{1}{2} (\sigma^x)^2 \partial_{xx} g = r g \\ g(T, x) = \Phi(x) \end{cases}$$

$\uparrow$
 m.p.r.
 $\lambda = \frac{\mu^H - r}{\sigma^H}$

Feynman-Kac $\Rightarrow$

T

$$q(t, x) = \mathbb{E}^{\mathbb{Q}} \left[e^{-\int_t^T r(u, X_u) du} \Phi(X_T) \mid X_t = x \right]$$

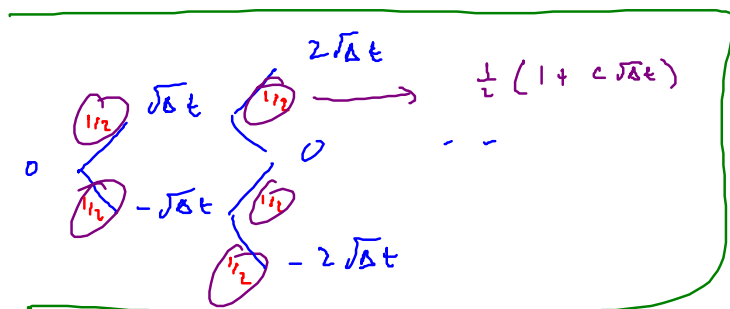
$$\text{and } dX_t = (\mu^x(t, X_t) - \sigma^x(t, X_t) \lambda(t, X_t)) dt$$

$$+ \sigma^x(t, X_t) d\hat{W}_t$$

— $\mathbb{Q}$ -B.m.m.

recall $dX_t = \mu^x(t, X_t) dt + \sigma^x(t, X_t) dW_t$

— $\mathbb{P}$ -B.m.m.



suggests that

$$d\hat{W}_t = \lambda(t, X_t) dt + dW_t$$

intuition is that $\hat{W}_t$ is a drift adjusted W_t .
(m.p.r.)

how to relate $\mathbb{P}$ to $\mathbb{Q}$?

$$\left(\frac{d\mathbb{Q}}{d\mathbb{P}} \right)_T = \exp \left\{ -\frac{1}{2} \int_0^T \lambda_u^2 du - \int_0^T \lambda_u dW_u \right\}$$

is a Radon-Nikodym derivative.

$$A \in \mathcal{F}_T$$

→ event measurable

$$\mathbb{Q}(A) = \mathbb{E}^{\mathbb{Q}} [\mathbb{1}_A] = \mathbb{E}^{\mathbb{P}} \left[\mathbb{1}_A \left(\frac{d\mathbb{Q}}{d\mathbb{P}} \right)_T \right]$$

$$\int_{\omega \in \Omega} d\mathbb{Q}(\omega) = \int_{\omega \in \Omega} \left(\frac{d\mathbb{Q}}{d\mathbb{P}} \right)_T(\omega) d\mathbb{P}(\omega)$$

$$\mathbb{Q}(A | \mathcal{F}_t) = \mathbb{E}^{\mathbb{Q}} [\mathbb{1}_A | \mathcal{F}_t]$$

$$= \frac{E^P \left[\mathbb{1}_A \left(\frac{dQ}{dP} \right)_T \mid \mathcal{F}_t \right]}{E^P \left[\left(\frac{dQ}{dP} \right)_T \mid \mathcal{F}_t \right]} \rightarrow \eta_t \text{ is } P\text{-m.t.g.}$$

$$S \begin{cases} S e^{\sigma \sqrt{\Delta t}} \\ S e^{-\sigma \sqrt{\Delta t}} \end{cases}$$

$$p = \frac{1}{2} \left(1 + \frac{r - \frac{1}{2}\sigma^2}{\sigma} \sqrt{\Delta t} \right)$$

$$q = \frac{1}{2} \left(1 + \frac{r - \frac{1}{2}\sigma^2}{\sigma} \sqrt{\Delta t} \right)$$

$$\left(\frac{dQ}{dP} \right) (x_1 = +1) = \frac{q}{p}$$

$$\left(\frac{dQ}{dP} \right) (x_1 = -1) = \frac{1-q}{1-p}$$

$$\begin{array}{ccc} P & \frac{dQ}{dP} & Q \\ \downarrow & \downarrow & \downarrow \\ p & \times \frac{q}{p} & = q \end{array}$$

$$(1-p) \cdot \left(\frac{1-q}{1-p} \right) = 1-q$$

Girsanov's Theorem:

$$\hat{W}_t = \int_0^t \lambda(t, X_u) du + W_t$$

is a Q -B.m.t.

$$Z \underset{\mathbb{P}}{\sim} \mathcal{N}(0, 1)$$

$$\frac{d\mathbb{Q}}{d\mathbb{P}} = e^{-\frac{1}{2}\lambda^2 - \lambda Z}$$

here $\lambda = \text{const.}$

what is the $\mathbb{Q}$ -distribution of Z ?

→ compute char. fn / m.g.f.

$$\begin{aligned} \mathbb{E}^{\mathbb{Q}}[e^{uZ}] &= \mathbb{E}^{\mathbb{P}}\left[e^{uZ} \left(\frac{d\mathbb{Q}}{d\mathbb{P}}\right)\right] \\ &= \mathbb{E}^{\mathbb{P}}\left[e^{uZ} e^{-\frac{1}{2}\lambda^2 - \lambda Z}\right] \\ &= e^{-\frac{1}{2}\lambda^2} \mathbb{E}^{\mathbb{P}}\left[e^{(u-\lambda)Z}\right] \\ &= e^{-\frac{1}{2}\lambda^2} e^{\frac{1}{2}(u-\lambda)^2} \\ &= e^{\frac{1}{2}u^2 - u\lambda} \end{aligned}$$

$$\therefore Z \underset{\mathbb{Q}}{\sim} \mathcal{N}(-\lambda; 1)$$

$$Z \underset{\mathbb{P}}{\sim} \mathcal{N}(0; 1)$$

$$\text{set } \hat{Z} = \lambda + Z$$

$$\text{then } \hat{Z} \sim \mathcal{N}(0; 1)$$



Vasicek Models:

$$dr_t = \kappa(\theta - r_t)dt + \sigma dW_t \quad \text{IP - B.m.m.}$$

$$\rightarrow r_t = r_0 e^{-\kappa t} + \theta(1 - e^{-\kappa t}) + \sigma \int_0^t e^{-\kappa(t-u)} dW_u$$

$$V_t = \mathbb{E}^Q \left[e^{-\int_t^T r_u du} \Phi(r_T) \mid \mathcal{F}_t \right]$$

$$\begin{aligned} dr_t &= \kappa(\theta - r_t)dt + \sigma(d\tilde{W}_t - \lambda(t, r_t)dt) \\ &= (\kappa\theta - \kappa r_t - \sigma\lambda(t, r_t))dt + \sigma d\tilde{W}_t \\ &\quad \text{Q - B.m.m.} \\ &\quad \text{a + b}r_t \end{aligned}$$

$$= \hat{\kappa}(\hat{\theta} - r_t)dt + \sigma d\tilde{W}_t$$

$$\begin{aligned} \hat{\kappa} &= \kappa + b\sigma \\ \hat{\theta} &= \frac{\kappa\theta - a\sigma}{\kappa + b\sigma} \end{aligned}$$

$$\text{so } r_t = r_0 e^{-\hat{\kappa}t} + \hat{\theta}(1 - e^{-\hat{\kappa}t}) + \sigma \int_0^t e^{-\hat{\kappa}(t-u)} d\tilde{W}_u$$

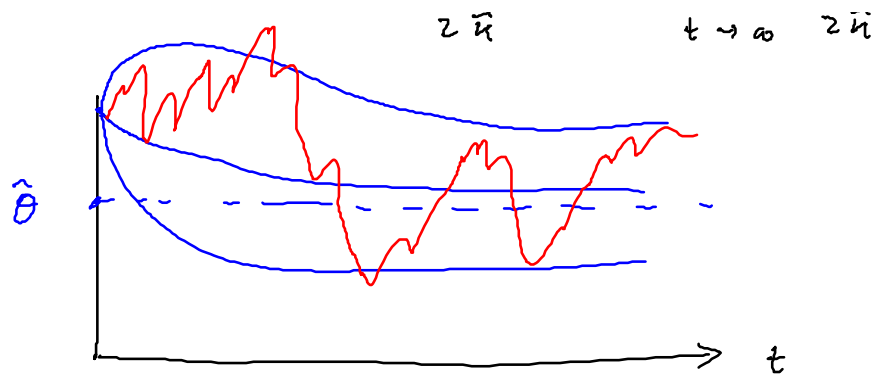
$$\mathbb{E}^Q[r_t] = r_0 e^{-\hat{\kappa}t} + \hat{\theta}(1 - e^{-\hat{\kappa}t})$$

$$\mathbb{V}^Q[r_t] = \mathbb{V}^Q \left[\sigma \int_0^t e^{-\hat{\kappa}(t-u)} d\tilde{W}_u \right]$$

$$= \sigma^2 \mathbb{E}^Q \left[\left(\int_0^t e^{-\hat{\kappa}(t-u)} d\tilde{W}_u \right)^2 \right]$$

$$= \sigma^2 \mathbb{E}^Q \left[\int_0^t e^{-2\hat{\kappa}(t-u)} du \right] \quad \text{Ito's isometry}$$

$$= \sigma^2 \frac{1 - e^{-2\hat{\kappa}t}}{2\hat{\kappa}} \rightarrow \frac{\sigma^2}{2\hat{\kappa}}$$



value a bond ...

$$P_t(\tau) = \mathbb{E}^Q \left[e^{-\int_t^\tau r_u du} \mid \mathcal{F}_t \right]$$

payoff = 1 $\neq r_\tau$

$$dr_t = \hat{\kappa} (\hat{\theta} - r_t) dt + \sigma d\hat{W}_t$$

$$r_T - r_t = \hat{\kappa} \hat{\theta} (\tau - t) - \hat{\kappa} \int_t^\tau r_u du + \sigma \int_t^\tau d\hat{W}_u$$

$$\Rightarrow \int_t^\tau r_u du = \hat{\theta} (\tau - t) - \frac{1}{\hat{\kappa}} (r_T - r_t) + \frac{\sigma}{\hat{\kappa}} \int_t^\tau d\hat{W}_u$$

$$r_T = r_t e^{-\hat{\kappa}(\tau-t)} + \hat{\theta} (1 - e^{-\hat{\kappa}(\tau-t)}) + \sigma \int_t^\tau e^{-\hat{\kappa}(\tau-u)} d\hat{W}_u$$

$$\int_t^\tau r_u du = \hat{\theta} \left[(\tau - t) - \frac{1 - e^{-\hat{\kappa}(\tau-t)}}{\hat{\kappa}} \right] + \frac{1 - e^{-\hat{\kappa}(\tau-t)}}{\hat{\kappa}} r_t + \frac{\sigma}{\hat{\kappa}} \int_t^\tau (1 - e^{-\hat{\kappa}(\tau-u)}) d\hat{W}_u$$

$$\sim N(\mu; \sigma^2)$$

$$V^2 = \frac{\sigma^2}{\hat{\kappa}^2} \mathbb{E}^Q \left[\int_t^\tau (1 - e^{-\hat{\kappa}(\tau-u)})^2 du \right]$$

$$= \frac{\sigma^2}{\hat{\kappa}^2} \left((\tau - t) - 2 \frac{1 - e^{-\hat{\kappa}(\tau-t)}}{\hat{\kappa}} + \frac{1 - e^{-2\hat{\kappa}(\tau-t)}}{2\hat{\kappa}} \right)$$

$$\therefore P_t(\tau) = \mathbb{E}^Q \left[e^{-\int_t^\tau r_u du} \mid \mathcal{F}_t \right]$$

$$= \mathbb{E}^Q \left[e^{-(m + vZ)} | \mathcal{F}_t \right]$$

$$Z \sim \mathcal{N}(0,1)$$

$$= e^{-m + \frac{1}{2}v^2}$$

$$= \exp \left\{ A_t(\tau) - B_t(\tau) \hat{r}_t \right\}$$

$$\hookrightarrow \frac{1 - e^{-\hat{r}(\tau-t)}}{\hat{r}}$$

only source of uncertainty.

Vasicek is an Affine model

recall that

$$\begin{cases} \partial_t P + \hat{r}(\hat{\theta} - r) \partial_r P + \frac{1}{2} \sigma^2 \partial_{rr} P = r P \\ P(T, r) = 1 \end{cases}$$

assume that $P(t, r; T) = \exp\{ \underbrace{A_t(T) - B_t(T) r}_{\text{fns only of } t \text{ not } r} \}$
(Affine Form)

$$\partial_t P = (\dot{A} - \dot{B} r) P$$

$$\partial_r P = -B P$$

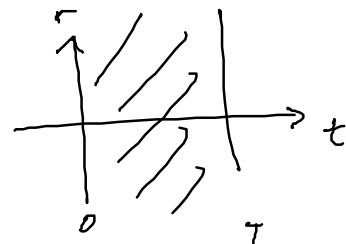
$$\partial_{rr} P = B^2 P$$

$$(\dot{A} - \dot{B} r) + \hat{r}(\hat{\theta} - r)(-B) + \frac{1}{2} \sigma^2 B^2 = r$$

$$(\dot{A} - \hat{r} \hat{\theta} B + \frac{1}{2} \sigma^2 B^2)$$

$$+ (-\dot{B} + \hat{r} B - 1) r = 0$$

must hold $\forall t, r$



$$\begin{aligned} \Leftrightarrow \textcircled{1} \quad \dot{A} - \hat{r} \hat{\theta} B + \frac{1}{2} \sigma^2 B^2 &= 0 \\ + \textcircled{2} \quad -\dot{B} + \hat{r} B - 1 &= 0 \end{aligned} \quad \left. \begin{array}{l} \text{Ricatti Equations} \\ \text{ODEs.} \end{array} \right\}$$

$$\text{b. c.} \quad A_T(T) - B_T(T) r = 0 \quad \forall r$$

$$\Leftrightarrow A_T(T) = 0 \quad + \quad B_T(T) = 0$$

$$B_t(T) = \frac{1 - e^{-\hat{r}(T-t)}}{\hat{r}}$$

$$\textcircled{2} \Rightarrow \dot{B} = \hat{r} B - 1$$

$$\Rightarrow \frac{\dot{B}}{\hat{h} B - 1} = 1 \Rightarrow \frac{1}{\hat{h}} d(\ln(\hat{h} B - 1)) = 1$$

$$\Rightarrow \frac{1}{\hat{h}} \left[\ln(\hat{h} B_T(T) - 1) - \ln(\hat{h} B_t(t) - 1) \right] = T - t$$

$$\Rightarrow -\ln(1 - \hat{h} B_t(t)) = \hat{h} (T - t)$$

$$\Rightarrow 1 - \hat{h} B_t(t) = e^{-\hat{h} (T - t)}$$

$$\Rightarrow B_t(t) = \frac{1 - e^{-\hat{h} (T - t)}}{\hat{h}}$$

$$\dot{A} - \hat{h} \hat{\theta} B + \frac{1}{2} \sigma^2 B^2 = 0$$

$$\Rightarrow A_T - A_t - \hat{h} \hat{\theta} \int_t^T B_u du + \frac{1}{2} \sigma^2 \int_t^T B_u^2 du = 0$$

$\hookrightarrow 0$

$$\Rightarrow A_t = -\hat{h} \hat{\theta} \int_t^T B_u du + \frac{1}{2} \sigma^2 \int_t^T B_u^2 du$$

= ...