Notes

- Homework 3 due on Wednesday, March 9
- Friday's class for answering questions re homework
- No office hour this Friday
- HW 2, Question 2: don't need (can't) solve explicitly for $\hat{\beta}$
- HW 2, Question 3: don't need to divide into training and test error
- HW 2, Question 4: I thought smoothing was on the β²s (256 of them), but it is perhaps on the x's directly

- "local" in R¹ is quite different that local in R^p
- Example: suppose each feature variable is uniformly distributed on (0, 1). If we want 10% of the sample in R¹, we need a window of length 0.1. In R^p, to get 10% of the volume, we need a box with edge length 0.1^{1/10} = 0.80, so on each axis we need a window of length 0.8.
- Example: N data points uniformly distributed on a unit ball in R^p. What is the distance to the nearest neighbour to the origin? Median is
- $(1 0.5^{1/N})^{1/p} \approx 0.52$ if p = 10, N = 500.
- Figures 2.6 and 2.7

- extend smoothing methods to p inputs, avoiding the curse of dimensionality
- retain interpretation, computationally feasible
- ► a 'linear' additive model has the form $E(Y | X_1, ..., X_p) = \mu(\underline{X}) = \alpha + \sum_{i=1}^p f_i(X_i)$
- *f_j* unspecified 'smooth' function, e.g. a smoothing spline, or a kernel regression function
- a 'generalized additive model' has the form $g\{\mu(\underline{X})\} = \alpha + \sum_{j=1}^{p} f_j(X_i)$
- ► examples of g(·) are g(µ) = log{µ/(1 − µ)} for binomial proportions, g(µ) = log µ for Poisson data, etc. (builds on generalized linear models as discussed in STA 410)

Fitting 'linear' additive models (§9.1.1.)

- ▶ first constrain f_j so that $\sum_{i=1}^N f_j(x_{ij}) = 0$, j = 1, ..., p
- ► penalized residual sum of squares $\sum_{i=1}^{N} \{y_i - \alpha - \sum_{j=1}^{p} f_j(x_{ij})\}^2 + \sum_{j=1}^{p} \lambda_j \int f_j''(t)^2 dt$
- backfitting: (Algorithm 9.1)

•
$$\hat{\alpha} = \frac{1}{N} \sum_{i=1}^{N} y_i$$
, $\hat{f}_j \equiv 0$, $j = 1, \dots, p$

• cycle through j = 1, ..., p, 1, ..., p until convergence:

$$\begin{aligned} \hat{y}_i &\longleftarrow \quad y_i - \hat{\alpha} - \sum_{k \neq j}^p \hat{f}_k(x_{ik}) \quad i = 1, \dots, N \\ \hat{f}_j &\longleftarrow \quad \mathcal{S}_j(y_i, x_{ij})_{i=1}^N \\ \hat{f}_j &\longleftarrow \quad \hat{f}_j - \frac{1}{N} \sum_{i=1}^N \hat{f}_j(x_{ij}) \end{aligned}$$

the last step to enforce the constraint in the presence of roundoff error

```
Fitting 'linear' additive models (§9.1.1.)
```

first constrain f_i so that ∑^N_{i=1} f_i(x_i) = 0, j = 1,...,p

 $\label{eq:second} \begin{array}{l} \text{postbarres} \\ \sum_{i=1}^{n} (I_i - \sigma_i \sum_{i=1}^{n} (A_i \sigma_i)^2 + \sum_{i=1}^{n} I_i \int_{i=1}^{n} (I_i^* \sigma_i^* \sigma_i^*) \\ \text{baskfitting} (Applithen B.1) \\ \text{baskfitting} (Applithen$

roundoff error

- replacement y_i is the residual from the current fit
- fitting to the residuals is analogous to multiple regression by successive partial regressions ($\S3.3$)
- iteratively reweighted least squares used for logistic regression in $\S 4.4.1$

- S is a cubic smoothing spline if we use penalized residual sum of squares
- could in principle be any smoothing operation: e.g. natural cubic spline or other regression spline, kernel regression function, loess, etc.
- claim (p.260) solution is unique if (x_{ij}) matrix of full column rank (theory project)
- can allow some terms to be ordinary linear regression terms; no smoothing needed
- can (in principle) allow some terms to be smooth functions of, e.g., pairs of inputs
- ► degrees of freedom for smoother S_j is df_j = trace(S_j) 1, where S_j is the N × N operator matrix (correctness of this still open)
- for generalized additive models, goal is to maximize the penalized log-likelihood, not minimize the penalized residual sum of squares

- combine the iteratively reweighted least squares algorithm for generalized linear models with Algorithm 9.1 (backfitting)
- model

$$\log \frac{\Pr(Y=1 \mid X)}{\Pr(Y=0 \mid X)} = \alpha + f_1(X_1) + \dots + f_p(X_p)$$

- initialize: â = log(y)/(1 y), where y is sample mean (proportion of 1's); f_j ≡ 0
 - $\hat{\eta}_i = \hat{\alpha} + \sum_j \hat{f}_j(\boldsymbol{x}_{ij}), \quad \hat{\mu}_i = 1/\{1 + \exp(-\hat{\mu}_i)\}$
 - working variable $z_i = \hat{\eta}_i + \frac{y_i \hat{\mu}_i}{\hat{\mu}_i(1 \hat{\mu}_i)}$
 - working weight $\hat{w}_i = \hat{\mu}_i (1 \hat{\mu}_i)$
 - use Alg. 9.1 to fit an additive model to z_i with weights w_i
- update $\hat{\eta}_i$ and continue until convergence

> hr.gam <- gam(chd~s(sbp)+s(tobacco)+s(ldl)+famhist+s(obesity</pre>

> hr.gam\$coef (Intercept) famhistPresent s(sbp).1 s(sbp).2 -1.314442e+009.479920e-01 3.882599e-01 2.927006e-02 s(sbp).3 s(sbp).4 s(sbp).5 s(sbp).6 -2.103390e-029.864767e-03 -6.265013e-03 -2.081766e-03 s(sbp).7 s(sbp).10 s(sbp).8 s(sbp).9 3.421593e-03 2.544205e-04 -3.386699e-01 1.413812e-01 s(tobacco).1 s(tobacco).2 s(tobacco).3 s(tobacco).4 4.730698e-10 2.510070e-11 1.280031e-11 -2.759787e-11 s(tobacco).5 s(tobacco).6 s(tobacco).7 s(tobacco).8 -5.695848e-11 -8,963317e-12 -2.058901e-12 1.842881e-12 s(tobacco).9 s(tobacco).10 s(ldl).1 s(ldl).2 -4.983894e - 103.713993e-01 5.901141e-08 -1.337292e-10 s(ldl).3 s(ldl).4 s(ldl).5 s(ldl).6 -7.556864e-098.533137e-10 -2.491124e-10 4.035828e-10 s(ldl).7 s(ldl).8 s(ldl).9 s(ldl).10 7.538201e-11 1.255975e-10 5.284967e-08 4.021833e-01

```
> hr.gam$sp
[1] 1.386301e+04 7.306222e+10 1.076798e+08 6.958563e+01 1.6240
[6] 5.315837e+01
> plot.gam(hr.gam)
> hr.gam
Family: binomial
Link function: logit
Formula:
chd \tilde{s}(sbp) + s(tobacco) + s(ldl) + famhist + s(obesity) + s(
    s(age)
Estimated degrees of freedom:
 1.713315 \ 1 \ 1.000000 \ 2.097546 \ 1 \ 3.984891 \ total = 12.79575
UBRE score: 0.02242598
```

- if estimated degrees of freedom near 1, then linear fit is satisfactory (e.g. tobacco)
- if the plotted confidence band includes zero, then term is not needed (e.g. alcohol)
- generalized cross-validation is used to estimate each smoothing parameter (Wood, 2001)
- this is not exactly the same as the back-fitting algorithm described in the text, but seems to be more reliable
- UBRE is a version of generalized cross-validation recommended for binomial data
- from Wood (2001): if the GCV score drops when a term is omitted, and the confidence band includes zero, then the term is not needed in the model
- the default is 10 knots for a smooth term if unspecified

- each smooth can be specified as
 - s (x): default 10 knots + penalty for smoothness
 - s(x, k=5, fx=TRUE) or s(x, 5|f): force 5 knots (4 df) for x, no shrinkage permitted
 - s (x, 20): start with 20 knots (maximum 19 df), and choose fewer by GCV
- the default basis is the thin plate basis; to get cubic regression splines use argument bs="cr"

- example in text uses "spam" data from UC Irvine: 4601 instances, training set of size 3065 (indicators available on web site)
- binary response (1=spam, 0= not spam), cubic splines, 4df per predictor

		predicted class					
► Table 9.1:	true class	email	spam				
	email	58.5%	2.5%				
	spam	2.7 %	36.2%				
► linear logistic regression has test error of 7.6%							

▶ <u>Table 9.2:</u>

Name	num.	df	coef	se	Z	nonlinear <i>P</i> -value			
Positive effects									
our	5	3.9	0.566	0.114	4.970	0.052			
over	7	3.9	0.244	0.195	1.249	0.004			
САРМАХ	56	3.8	0.247	0.228	1.080	0.000			
САРТОТ	47	4.0	0.755	0.165	4.566	0.063			

see Figure 9.1

Tree-based methods (§9.2)

- §9.2.1, 9.2.2 regression trees (y is continuous)
- formalism: $\hat{f}(x) = \sum_{m=1}^{M} c_m \mathbf{1}\{x \in \mathcal{R}_m\}$
- *R_m* is a subspace of *R^p* obtained by partitioning the feature space using binary splits
- ▶ if \mathcal{R}_m is fixed, then the optimal choice of c_m to minimize $\sum \{y_i f(x_i)\}^2$ is just $\operatorname{ave}(y_i \mid x_i \in \mathcal{R}_m)$
- trees are 'grown' in a greedy fashion, starting with any node and finding the variable to split on X_j, j = 1,..., p and the split point s
- to minimize squared error after splitting

$$\min_{j,s} \left[\min_{c_1} \sum_{x_i \in R_1(j,s)} (y_i - c_1)^2 + \min_{c_2} \sum_{x_i \in R_2(j,s)} (y_i - c_2)^2 \right]$$

$$R_1(j,s) = \{X \mid X_j \le s\}, \quad R_2(j,s) = \{X \mid X_j > s\}$$

$$\hat{c}_1 = \operatorname{ave}\{y_i \mid x_i \in R_1(j,s)\}, \quad \hat{c}_2 = \operatorname{ave}\{y_i \mid x_i \in R_2(j,s)\}$$

Tree-based methods (§9.2)

 trees are grown to be quite large and then pruned, using a cos-complexity criterion

$$C_{\alpha}(T) = \sum_{m=1}^{|T|} N_m Q_m(T) + \alpha |T|$$
 (9.16)

$$\blacktriangleright \quad Q_m(T) = \frac{1}{N_m} \sum_{x_i \in R_m} (y_i - \hat{c}_m)^2, \quad \hat{c}_m = \frac{1}{N_m} \sum_{x_i \in R_m} y_i$$

- |T| is number of terminal nodes
- $C_{\alpha}(T)$ trades off fit to data Q_m and tree size T
- For each α there is a pruning strategy
- Choose \(\alpha\) by 5 or 10 fold CV
- see Figure 9.5 for a classification tree
- more on trees and MARS on March 16
- next week neural networks (Ch 11)