Aspects of Likelihood Inference

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ACCORT BERNOULLI, both the Agencie the Neural Neura



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Models and likelihood

- Model for the probability distribution of y given x
- Density f(y | x) with respect to, e.g., Lebesgue measure
- ▶ Parameters for the density $f(y|x;\theta)$, $\theta = (\theta_1, \dots, \theta_d)$
- Likelihood function $L(\theta; y^0) \propto f(y^0; \theta)$
- often $\theta = (\psi, \lambda)$
- θ could have very large dimension, d > n typically y = (y₁,..., y_n)
- θ could have infinite dimension E(y | x) = θ(x) 'smooth',
 in principle

Why likelihood?

- makes probability modelling central
- emphasizes the inverse problem of reasoning from y⁰ to θ or f(·)
- suggested by Fisher as a measure of plausibility

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Royall, 1994
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 $\begin{array}{ll} L(\hat{\theta})/L(\theta) \in (1,3) & \text{very plausible;} \\ L(\hat{\theta})/L(\theta) \in (3,10) & \text{implausible;} \\ L(\hat{\theta})/L(\theta) \in (10,\infty) & \text{very implausible} \end{array}$

- converts a 'prior' probability π(θ) to a posterior π(θ | y) via Bayes' Theorem
- provides a conventional set of summary quantities for inference based on properties of the postulated model

Widely used



Cold Regions Science and Technology

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In Press, Accepted Manuscript - Note to users



A Generalized Probabilistic Model of Ice Load Peaks on Ship Hulls in Broken-Ice Fields

A. Suyuthia, B.J. Leiraa, K. Riskab, c

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Diversification of *Scrophularia* (Scrophulariaceae) in the Western Mediterranean and Macaronesia – Phylogenetic relationships, reticulate evolution and biogeographic patterns

Agnes Scheunert 📥 🛛 🗠, Günther Heubl

Systematic Botany and Mycology, Department Biology I, Ludwig-Maximilians-University, GeoBio Center LMU, Menzinger Strasse 67, 80638 Munich, Germany

Empirical growth curve estimation considering multiple seasonal compensatory growths of body weights in Japanese Thoroughbred colt and fillies.

(PMID:24085406)

	Abstract	Citations 2	BioEntities (2)	Related Articles	External Links 🛿	
Onoda T, Yamamoto R, Sawmura K, Inoue Y, Murase H, Nambo Y, Tozaki T, Matsui A, Miyake T, Hirai N Comparative Agricultural Sciences, Graduate School of Agriculture, Kyoto University, Kyoto 606-8502, Journal of Animal Science [2013]						an
Ţ	ype: Journal Arti	cle				



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Journal of Networks, Vol 8, No 10 (2013), 2220-2226, Oct 2013 doi:10.4304/jnw.8.10.2220-2226

Low-Complexity Carrier Frequency Offset Estimation Algorithm in TD-LTE

Dan Wang, Weiping Shi, Xiaowen Li



National Post, Toronto, Jan 30 2008

... why likelihood?

- likelihood function depends on data only through sufficient statistics
- "likelihood map is sufficient"
 Fraser & Naderi, 2006
- gives exact inference in transformation models
- "likelihood function as pivotal" Hinkley, 1980
- provides summary statistics with known limiting distribution
- likelihood function + sample space derivative gives better approximate inference

$$f(\hat{\theta}|a;\theta) = L(\theta) / \int L(\theta) d\theta$$

for $f(\theta) = L(\theta; \hat{\theta}, a) / \int L(\theta; \hat{\theta}, a) d\theta$

Derived quantities



Approximate pivots scalar parameter of interest

- profile log-likelihood $\ell_{p}(\psi) = \ell(\psi, \hat{\lambda}_{\psi})$
- $\theta = (\psi, \lambda); \hat{\lambda}_{\psi}$ constrained maximum likelihood estimator $\hat{\Theta} \theta \sim \mathcal{N}(0, j^{-1}(\hat{\Theta})) \oplus (\hat{\Theta} \theta) j^{2}(\hat{\Theta})$
 - $r_{e}(\psi; y) = (\hat{\psi} \psi) j_{p}^{1/2}(\hat{\psi}) \quad \sim \quad N(0, 1)$ $r(\psi; y) = \pm \sqrt{[2\{\ell_{\mathsf{D}}(\hat{\psi}) - \ell_{\mathsf{D}}(\psi)\}]} \quad \sim \quad N(0, 1)$ $\pi_{\mathsf{m}}(\psi \mid \mathbf{y}) \quad \sim \quad N\{\hat{\psi}, j_{\mathsf{p}}^{-1/2}(\hat{\psi})\}$



 $\theta = (\Psi, \lambda)$

 $\sim \mathcal{N}(\mathbf{0},\mathbf{1})$



... approximate pivots scalar parameter of interest

- profile log-likelihood $\ell_{p}(\psi) = \ell(\psi, \hat{\lambda}_{\psi})$
- $\theta = (\psi, \lambda); \hat{\lambda}_{\psi}$ constrained maximum likelihood estimator

$$y_{i} \quad id \quad \frac{1}{P(4)} \left(\frac{\psi}{\lambda}\right)^{4} y_{i}^{4} = \frac{4\psi_{i}}{\lambda}$$

$$\theta = (4, \lambda) \quad Gaume (shope 4, mean \lambda)$$

$$R(4, \lambda) = \sum for f(y_{i}, 4, \lambda)$$

$$= -n lop F(4) + \dots + 4 \sum lop y_{i} - \frac{\psi}{\lambda} y_{i}$$

$$= -n lop F(4) + \dots + 4 \sum lop y_{i} - \frac{\psi}{\lambda} y_{i}$$

... approximate pivots scalar parameter of interest

• profile log-likelihood $\ell_{p}(\psi) = \ell(\psi, \hat{\lambda}_{\psi})$

Aspects of Li

• $\theta = (\psi, \lambda); \hat{\lambda}_{\psi}$ constrained maximum likelihood estimator

$$\begin{aligned} r_{\theta}(\psi; y) &= (\hat{\psi} - \psi) j_{p}^{1/2}(\hat{\psi}) & \sim & N(0, 1) \left\{ 1 + \hat{\theta}_{p} \left(\frac{1}{\sqrt{n}} \right\} \\ r(\psi; y) &= \pm \sqrt{[2\{\ell_{p}(\hat{\psi}) - \ell_{p}(\psi)\}]} & \sim & N(0, 1) \\ & \pi_{m}(\psi \mid y) & \sim & N\{\hat{\psi}, j_{p}^{-1/2}(\hat{\psi})\} \end{aligned}$$

The problem with profiling

- ℓ_p(ψ) = ℓ(ψ, λ̂_ψ) used as a 'regular' likelihood, with the usual asymptotics
- neglects errors in the estimation of the nuisance parameter
- can be very large when there are many nuisance parameters
- ► example: normal theory linear regression ô² = RSS/n usual estimator RSS/(n - k) k the number of regression coefficients
- badly biased if k large relative to n
- inconsistent for σ^2 if $k \to \infty$ with *n* fixed
- example fitting of smooth functions with large numbers of spline coefficients

Conditional and marginal likelihoods

 $f(\mathbf{y}; \psi, \lambda) \propto f_1(\mathbf{s} \mid t; \psi) f_2(t; \lambda)$

- L(ψ, λ) ∝ L_c(ψ)L_m(λ), where L₁ and L₂ are genuine likelihoods, i.e. proportional to genuine density functions
- L_p(ψ) is a conditional likelihood L_c(ψ), and estimation of λ has no impact on asymptotic properties
- ▶ *s* is conditionally sufficient , *t* is marginally ancillary, for ψ
- hardly ever get so lucky
- but might expect something like this to hold approximately, which it does, and this is implemented in r^{*}_F formula automatically
 Brazzale, Davison, R 2007