Notes on Q1, Homework 1.

Question

Suppose that random variables Y_r follow the first order autoregressive process

$$Y_r = \mu + \rho(Y_{r-1} - \mu) + \epsilon_r,$$

where $\epsilon_1, \ldots, \epsilon_n$ are i.i.d. $N(0, \sigma^2)$ and $|\rho| < 1$. Write down the likelihood for data y_1, \ldots, y_n in the cases where the initial value y_0 is

- (a) a given constant;
- (b) normally distributed with mean μ and variance $\sigma^2/(1-\rho^2)$;
- (c) assumed equal to y_n .

Find the minimal sufficient statistic for $\theta = (\mu, \rho, \sigma^2)$ in each case.

Solution

The question in C&H actually reads, "Write down the likelihood for data y_0, \ldots, y_n ..."; in this correctly worded version the solution goes as follows:

$$f(y_0, \dots, y_n; \theta) = \frac{1}{(\sqrt{2\pi}\sigma)^{n-1}} \prod_{i=1}^n \exp\left[-\frac{1}{2\sigma^2} \{y_i - \mu - \rho(y_{i-1} - \mu)\}^2\right] f(y_0; \theta)$$

writing the joint density as a product of conditionals, and using the Markov property.

The exponent when squared involves the following statistics:

$$\sum_{i=1}^{n} y_i^2, \sum_{i=1}^{n} y_{i-1}^2, \sum_{i=1}^{n} y_i, \sum_{i=1}^{n} y_{i-1}, \sum_{i=1}^{n} y_i y_{i-1}.$$
 (1)

Since $\sum_{i=1}^{n} y_{i-1} = \sum_{i=0}^{n-1} y_i$, the third and fourth terms can be computed from $\sum_{i=1}^{n} y_i, y_n, y_0$, and the 1st and 2nd terms can be computed from $\sum_{i=1}^{n} y_i^2, y_n, y_0$ as well. Thus (1) is equivalent to

$$\left(\sum_{i=1}^{n} y_{i}^{2}, \sum_{i=1}^{n} y_{i}, \sum_{i=1}^{n} y_{i}y_{i-1}, y_{0}, y_{n}\right).$$

$$(2)$$

In (a), $f(y_0)$ is a point mass at y_0 , so no additional functions of the data are needed to compute the log-likelihood function, and no simplification is available either. In (b) $f(y_0; \theta)$ depends on y_0^2 and y_0 , but again these already appear (2) so no additional functions are needed, nor are there any simplifications. In (c), when $y_0 = y_n$, so $f(y_0)$ is a point mass at y_n , then $\sum_{i=0}^{n-1} y_i = \sum_{i=1}^n y_i$, and similarly for $\sum_{i=1}^{n-1} y_i^2$, so that the endpoint corrections y_0, y_n are not needed, and we have a 3-dimensional sufficient statistic.

In (a) strictly speaking y_0 is not part of the sufficient statistic, because it is a fixed constant, although the solution given by C&H doesn't make this distinction.

In the version of the question that I gave, the joint density is

$$f(y_1, \dots, y_n; \theta) = \frac{1}{(\sqrt{2\pi}\sigma)^{n-1}} \prod_{i=2}^n \exp\left[-\frac{1}{2\sigma^2} \{y_i - \mu - \rho(y_{i-1} - \mu)\}^2\right] f(y_1; \theta),$$

and $f(y_1; \theta) = \int f(y_1 \mid y_0; \theta) f(y_0; \theta) dy_0$. The product term now depends on

$$\sum_{i=2}^{n} y_i, \sum_{i=2}^{n} y_i^2, \sum_{i=2}^{n} y_{i-1}, \sum_{i=2}^{n} y_{i-1}^2, \sum_{i=2}^{n} y_i y_{i-1}.$$
 (3)

In the case that y_0 is fixed, $f(y_1)$ is the density of a $N(\mu + \rho(y_0 - \mu), \sigma^2)$, so the joint density depends on

$$\sum_{i=1}^{n} y_i^2, \sum_{i=1}^{n} y_i, \sum_{i=1}^{n} y_i y_{i-1}, y_0, y_n,$$

as above, although again y_0 isn't strictly speaking a statistic.

In the case that y_0 follows the stationary distribution given in (b), then so does y_1 , in which case the joint density has an exponent that depends on

$$\sum_{i=1}^{n} y_i^2, \sum_{i=1}^{n} y_i, y_n, \sum_{i=2}^{n} y_i y_{i-1},$$
(4)

which is a bit different than for the likelihood based on (y_0, \ldots, y_n) .

Finally, in the case that $y_0 = y_n$, we don't get the simplification that we do for the likelihood based on (y_0, \ldots, y_n) , because the sums start

at 1. (We would if I had written " $y_1 = y_n$ ".) David F showed that the marginal distribution of y_1 in this case is $N(\mu, \beta)$, where $\beta = \sum_k \rho^{2(n-k+1)\sigma^2}$. This then contributes a term as in (b), and no simplification is possible.

I didn't mark this very rigidly – most people wrote down $L(\theta; y_0, \ldots, y_n)$ without being very specific about it. Let me know if I overlooked anything in your solution.

These statistics are minimal sufficient because they determine the likelihood function.