Approximate Likelihoods

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Models and likelihood

- ▶ Model for the probability distribution of y given x
- ▶ Density $f(y \mid x)$ with respect to, e.g., Lebesgue measure
- ▶ Parameters for the density $f(y|x;\theta)$, $\theta = (\theta_1, \dots, \theta_d)$
- ▶ Data $y = (y_1, ..., y_n)$ often independent
- ► Likelihood function $L(\theta; y) \propto f(y; \theta)$ $(y_1, ..., y_n)$
- ▶ log-likelihood function $\ell(\theta; y) = \log L(\theta; y)$
- often $\theta = (\psi, \lambda)$
- θ could have very large dimension, d > n
- lacktriangleright heta could have infinite dimension in principle

$$E(y \mid x) = \theta(x)$$
 'smooth'

Why likelihood?

- makes probability modelling central
- emphasizes the inverse problem of reasoning from y to θ or $f(\cdot)$
- suggested by Fisher as a measure of plausibility

Royall, 1997

$$\begin{array}{ll} L(\hat{\theta})/L(\theta) \in (1,3) & \text{very plausible;} \\ L(\hat{\theta})/L(\theta) \in (3,10) & \text{implausible;} \\ L(\hat{\theta})/L(\theta) \in (10,\infty) & \text{very implausible} \end{array}$$

- converts a 'prior' probability $\pi(\theta)$ to a posterior $\pi(\theta \mid y)$ via Bayes' Theorem
- provides a conventional set of summary quantities: maximum likelihood estimator, score function, ...

... why likelihood?

- likelihood function depends on data only through sufficient statistics
- "likelihood map is sufficient"

Fraser & Naderi, 2007

- gives exact inference in transformation models
- "likelihood function as pivotal"

Hinkley, 1980

- provides summary statistics with known limiting distribution
- leading to approximate pivotal functions, based on normal distribution
- likelihood function + sample space derivative gives better approximate inference
- basis for comparison of models, using AIC or BIC

Complicated likelihoods

generalized linear mixed models

GLM:
$$y_{ij} \mid u_i \sim \exp\{y_{ij}\eta_{ij} - b(\eta_{ij}) + c(y_{ij})\}$$

linear predictor:
$$\eta_{ij} = x_{ij}^{\mathrm{T}} \beta + z_{ij}^{\mathrm{T}} u_i$$
 $j=1,...n_i$; $i=1,...m$

random effects: $u_i \sim N_k(0, \Sigma)$

log-likelihood:

$$\begin{split} \ell(\beta, \Sigma) &= & \sum_{i=1}^m \left(y_i^{\mathrm{T}} X_i \beta - \frac{1}{2} \log |\Sigma| \right. \\ &+ & \log \int_{\mathbb{R}^k} \exp\{ y_i^{\mathrm{T}} Z_i u_i - \mathbf{1}_i^{\mathrm{T}} b(X_i \beta + Z_i u_i) - \frac{1}{2} u_i^{\mathrm{T}} \Sigma^{-1} u_i \} du_i \right) \end{split}$$

Ormerod & Wand 2012

Poisson
$$f(y_t \mid \alpha_t; \theta) = \exp(y_t \log \mu_t - \mu_t)/y_t!$$
 $\log \mu_t = \beta + \alpha_t$

autoregression

$$\alpha_t = \phi \alpha_{t-1} + \epsilon_t, \quad \epsilon_t \sim N(0, \sigma^2), \quad |\phi| < 1, \quad \theta = (\beta, \phi, \sigma^2)$$

likelihood

$$L(\theta; y_1, \dots, y_n) = \int \left(\prod_{t=1}^n f(y_t \mid \alpha_t; \theta) \right) f(\alpha; \theta) d\alpha$$

 $L_{approx}(\theta; y)$ via Laplace with some refinements

Davis & Yau, 2011

M/G/1 queue: exponential arrival times, general service times, single server

observations y_i : times between departures from the queue unobserved variables V_i : arrival time of customer i

model:

- $ightharpoonup V_1 \sim \mathsf{Exp}(\theta_3)$
- $\qquad \qquad V_i \mid V_{i-1} \sim V_{i-1} + \mathsf{Exp}(\theta_3)$
- $\begin{array}{ll} \blacktriangleright & Y_i \mid X_{i-1}, V_i \sim \mathsf{Uniform}\{\theta_1 + max(0, V_i X_{i-1}), \\ & \theta_2 + max(0, V_i X_{i-1})\} & X_i = \sum_{j=1}^i Y_j \quad G = U(\theta_1, \theta_2) \end{array}$

Likelihood

$$L(\theta; y) = \int \cdots \int f(v_1 \mid \theta) \prod_{i=1}^n f(v_i \mid v_{i-1}, \theta) \prod_{i=1}^n f(y_i \mid v_i, x_{i-1}, \theta) dv_1 \cdots dv_n$$

Shestopaloff & Neal, 2013 Fearnhead & Prangle, 2012

multivariate extremes: example, wind speed at d locations

vector observations:
$$(X_{1i}, \ldots, X_{di}), i = 1, \ldots, n$$

component-wise maxima:
$$Z_1, \ldots, Z_d; Z_j = \max(X_{j1}, \ldots, X_{jn})$$

 Z_j are transformed (centered and scaled)

joint distribution function:

$$\Pr(Z_1 \leq z_1, \dots, Z_d \leq z_d) = \exp\{-V(z_1, \dots, z_d)\}$$

 $V(\cdot)$ can be parameterized via Gaussian process models

likelihood : need the joint derivatives of $V(\cdot)$

combinatorial explosion

Davison et al., 2012

Ising model:

$$f(y;\theta) = \exp(\sum_{(j,k)\in E} \theta_{jk} y_j y_k) \frac{1}{Z(\theta)}$$

observations: $y_i = \pm 1$; binary property of a node i in a graph with K nodes

parameter: θ_{jk} measures strength of interaction between nodes i and j

E is the set of edges between nodes

partition function:
$$Z(\theta) = \sum_{y} \exp(\sum_{(j,k) \in E} \theta_{jk} y_j y_k)$$

Davison 2000 §6.2 Ravikumar et al. (2010) Xue et al. (2012)

What's a poor statistician to do?

- simplify the likelihood
 - composite likelihood
 - variational approximation
 - Laplace approximation to integrals
- change the mode of inference
 - quasi-likelihood
 - indirect inference
- simulate
 - approximate Bayesian computation
 - MCMC

Composite likelihood

- also called pseudo-likelihood
- reduce high-dimensional dependencies by ignoring them

for example, replace
$$f(y_{i1},\ldots,y_{ik};\theta)$$
 by pairwise marginal $\prod_{j < j'} f_2(y_{ij},y_{ij'};\theta)$, or conditional $\prod_i f_c(y_{ij} \mid y_{\mathcal{N}(ij)};\theta)$

Composite likelihood function

$$CL(\theta; y) \propto \prod_{i=1}^{n} \prod_{j < i'} f_2(y_{ij}, y_{ij'}; \theta)$$

 Composite ML estimates are consistent, asymptotically normal, not fully efficient
 Besag, 1975; Lindsay, 1988

Davis & Yau, 2011

Likelihood

$$L(\theta; y_1, \ldots, y_n) = \int \left(\prod_{t=1}^n f(y_t \mid \alpha_t; \theta) \right) f(\alpha; \theta) d\alpha$$

Composite likelihood

$$CL(\theta; y_1, \ldots, y_n) = \prod_{t=1}^{n-1} \int \int f(y_t \mid \alpha_t; \theta) f(y_{t+1} \mid \alpha_{t+1}; \theta) f(\alpha_t, \alpha_{t+1}; \theta) d\alpha_t d\alpha_{t+1}$$

- consecutive pairs
- ► Time-series asymptotic regime one vector *y* of increasing length
- Composite ML estimator still consistent, asymptotically normal, estimable asymptotic variance
- Efficient, relative to a Laplace-type approximation
- ► Surprises: AR(1), fully efficient; MA(1), poor; ARFIMA(0,d,0), ok

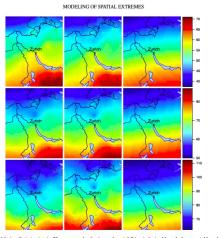
$$\Pr(Z_1 \leq z_1, \dots, Z_d \leq z_d) = \exp\{-V(z_1, \dots, z_d; \theta)\}$$

- pairwise composite likelihood used to compare the fits of several competing models
- model choice using "CLIC", an analogue of AIC

$$-2\log(\widehat{CL})+\operatorname{tr}(J^{-1}K)$$

- Davison et al. 2012 applied this to annual maximum rainfall at several stations near Zurich
- "fitting max-stable processes to spatial or spatio-temporal block maxima is awkward ... the use of composite likelihoods ... has become widely used" Davison & Huser

... Davison et al, 2012



175

Fig. 3. Mays of the (predictive) pointwise 25-year return level estimates for rainfull tomo obtained from the latent variable and max stable models. The top and bottom more show the lower and upper bound of the 95% pointwise credible-confidence internet. The middle row shows the predictive pointwise posterior mean and pointwise estimates. The left column corresponds to the latent variable model assuming Gamma(3, 3) prior on λ . The middle column assumed the less informative priors λ_0 —Camma(1, 100), λ_1 —Camma(1, 10) and λ_2 —Camma(1). The right column corresponds to the external topulal models.

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Example: Ising model

Ising model:

$$f(y; \theta) = \exp(\sum_{(j,k) \in E} \theta_{jk} y_j y_k) \frac{1}{Z(\theta)}$$

neighbourhood contributions

$$f(y_j \mid y_{(-j)}; \theta) = \frac{\exp(2y_j \sum_{k \neq j} \theta_{jk} y_k)}{\exp(2y_j \sum_{k \neq j} \theta_{jk} y_k) + 1}$$

penalized CL estimation based on sample $y^{(1)}, \dots, y^{(n)}$

$$\max_{\theta} \left\{ \sum_{i=1}^{n} \ell_{j}(\theta; y^{(i)}) - \sum_{j} \sum_{k} P_{\lambda}(|\theta_{jk}|) \right\}$$

Xue et al., 2012 Ravikumar et al., 2010

- ▶ in a Bayesian context, want $f(\beta \mid y)$ use an approximation $q(\beta)$
- dependence of q on y suppressed
- choose $q(\beta)$ to be
 - simple to calculate
 - close to posterior
- ▶ simple to calculate
 - $q(\beta) = \prod q_i(\beta_i)$
 - simple parametric family
- close to posterior: miminize Kullback-Leibler divergence

$$\mathit{KL}(q \mid\mid f_{post}) = \int q(\beta) \log\{q(\beta)/f(\beta \mid y)\} d\beta$$

close to posterior:

$$\min_{q} \int q(\beta) \log\{q(\beta)/f(\beta \mid y)\} d\beta = \min_{q} KL(q \mid\mid f_{post})$$

equivalent to

best LB for marginal f(y)

$$\max_{q} \int q(\beta) \log\{f(y,\beta)/q(\beta)\} d\beta$$

▶ in a likelihood context $\log f(y; \theta) = \log \int f(y \mid \beta; \theta) f(\beta) d\beta$

$$= \int q(\beta) \log\{f(y,\beta;\theta)/q(\beta)\}d\beta + KL(q \mid\mid f_{post})$$

 $\log f(y;\theta) \ge \int q(\beta) \log \{f(y,\beta;\theta)/q(\beta)\} d\beta$

here β represent random effects u, or b, or ...

log-likelihood:

$$\ell(\beta, \Sigma) = \sum_{i=1}^{m} \left(y_i^{\mathsf{T}} X_i \beta - \frac{1}{2} \log |\Sigma| \right)$$

$$+ \log \int_{\mathbb{R}^k} \exp\{ y_i^{\mathsf{T}} Z_i u_i - \mathbf{1}_i^{\mathsf{T}} b(X_i \beta + Z_i u_i) - \frac{1}{2} u_i^{\mathsf{T}} \Sigma^{-1} u_i \} du_i \right)$$

$$= \sum_{i=1}^{m} \left(y_i^{\mathsf{T}} X_i \beta - \frac{1}{2} \log |\Sigma| \right)$$

$$+ \log \int_{\mathbb{R}^k} \exp\{ y_i^{\mathsf{T}} Z_i u_i - \mathbf{1}_i^{\mathsf{T}} b(X_i \beta + Z_i u_i) - \frac{1}{2} u_i^{\mathsf{T}} \Sigma^{-1} u_i \} \frac{\phi_{\Lambda_i} (u - \mu_i)}{\phi_{\Lambda_i} (u - \mu_i)} du_i \right)$$
variational approx:

variational approx:

$$\begin{split} \ell(\beta, \Sigma) & \geq \sum_{i=1}^{m} \left(y_i^{\mathsf{T}} X_i \beta - \frac{1}{2} \log |\Sigma| \right) \\ & + \sum_{i=1}^{m} E_{u \sim N(\mu_i, \Lambda_i)} \left(y_i^{\mathsf{T}} Z_i u - \mathbf{1}_i^{\mathsf{T}} b(X_i \beta + Z_i u) - \frac{1}{2} u^{\mathsf{T}} \Sigma^{-1} u - \log \{ \phi_{\Lambda_i} (u - \mu_i) \} \right) \\ & \equiv \ell(\beta, \Sigma, \mu, \Lambda) \qquad \text{simplifies to k one-dim. integrals} \end{split}$$

Ormerod & Wand, 2012

•

$$\ell(\beta, \Sigma) \ge \ell(\beta, \Sigma, \mu, \Lambda)$$

variational estimate:

$$\ell(\tilde{\beta},\tilde{\Sigma},\tilde{\mu},\tilde{\Lambda}) = \text{arg max}_{\beta,\Sigma,\mu,\Lambda} \ell(\tilde{\beta},\tilde{\Sigma},\tilde{\mu},\tilde{\Lambda})$$

- inference for $\tilde{\beta}, \tilde{\Sigma}$? consistency? asymptotic normality?

 Hall, Ormerod, Wand, 2011; Hall et al. 2011
- emphasis on algorithms and model selection
 e.g. Tan & Nott, 2013, 2014
- ▶ VL: approx $L(\theta; y)$ by a simpler function of θ , e.g. $\prod q_j(\theta)$
- ▶ CL: approx $f(y; \theta)$ by a simpler function of y, e.g. $\prod f(y_j; \theta)$

Some Links between Variational Approximation and Composite Likelihoods?

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MSTGA, Paris, November 22-23, 2012

http://carlit.toulouse.inra.fr/AIGM/pub/Reunion_nov2012/MSTGA-1211-Robin.pdf

Laplace approximation

$$\ell(\theta; y) = \log \int f(y \mid b; \theta) g(b) db = \log \int \exp\{Q(b, y, \theta)\} db$$
, say

$$\ell_{Lap}(\theta; y) = Q(\tilde{b}, y, \theta) - \frac{1}{2} \log |Q''(\tilde{b}, y, \theta)| + c$$

using Taylor series expansion of $Q(\cdot, y, \theta)$ about \tilde{b}

simplification of the Laplace approximation leads to PQL:

$$\ell_{PQL}(\theta, b; y) = \log f(y \mid b; \theta) - \frac{1}{2}b^{T}\Sigma^{-1}b$$

Breslow & Clayton, 1993

to be jointly maximized over b and θ

and parameters in Σ

PQL can be viewed as linearizing E(y) and then using results for linear mixed models

Molenberghs & Verbeke, 2006

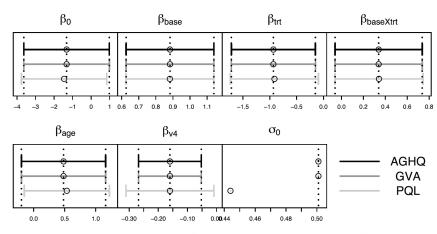


Figure 2. Point estimates and approximate 95% confidence intervals based on each of AGHQ, GVA, and PQL for the *Epilepsy* data random intercept model. The vertical dotted lines correspond to the AGHQ values.

implemented in lme4 as glmer, in MASS as glmmPQL

Ormerod & Wand, 2012

Extensions of Laplace approximations

- expansions valid with $p = o(n^{1/3})$ Shun & McCullagh, 1995
- expansions for mixed linear models to higher order

Raudenbush et al., 2000

use REML for variance parameters

Nelder & Lee, 1996

▶ integrated nested Laplace approximation
Rue et al., 2009

- ▶ model $f(y_i | \theta_i)$; prior $\pi(\theta | \theta)$ parameters and hyper-par
- ▶ posterior $\pi(\theta, \vartheta \mid y) \propto \pi(\theta \mid \vartheta)\pi(\vartheta) \prod f(y_i \mid \theta_i)$
- marginal posterior

$$\pi(\theta_i \mid y) = \int \underbrace{\pi(\theta_i \mid \vartheta, y)}_{\mathsf{Laplace}} \underbrace{\pi(\vartheta \mid y)}_{\mathsf{Laplace}} d\vartheta$$

Quasi-likelihood

simplify the model

$$\mathsf{E}(y_i;\theta) = \mu_i(\theta); \qquad \mathsf{Var}(y_i;\theta) = \phi \nu_i(\theta)$$

- consistent with generalized linear models
- example: over-dispersed Poisson responses
- ▶ PQL uses this construction, but with random effects Molenberghs & Verbeke, Ch. 14
- why does it work?
- score equations are the same as for a 'real' likelihood

hence unbiased

derivative of score function equal to variance function

special to GLMs

Indirect inference

composite likelihood estimators are consistent

under conditions ...

- ▶ because $\log CL(\theta; y) = \sum_{i=1}^{n} \sum_{j < j'} \log f(y_j, y_{j'}; \theta)$
- derivative w.r.t. θ has expected value 0
- what happens if an estimating equation $g(y; \theta)$ is biased?

▶
$$g(y_1,...,y_n; \tilde{\theta}_n) = 0;$$
 $\tilde{\theta}_n \to \theta^*$ $\exists g(Y; \theta^*) = 0$

•
$$\theta^* = \tilde{k}(\theta)$$
; invertible? $\theta = k(\theta^*)$ $\tilde{k}^{-1} \equiv k$

- ▶ new estimator $\hat{\theta}_n = k(\tilde{\theta}_n)$
- k(·) is a bridge function, connecting wrong value of θ
 to the right one
 Yi & R, 2010; Jiang & Turnbull, 2004

Smith, 2008

model of interest

$$y_t = G_t(y_{t-1}, x_t, \epsilon_t; \theta), \quad \theta \in \mathbb{R}^d$$

- likelihood is not-computable, but can simulate from the model
- ► simple (wrong) model

$$y_t \sim f(y_t \mid y_{t-1}, x_t; \theta^*), \quad \theta^* \in \mathbb{R}^p$$

- ▶ find the MLE in the simple model, $\hat{\theta}^* = \hat{\theta}^*(y_1, \dots, y_n)$, say
- use simulated samples from model of interest to find the 'best' β
- 'best' θ gives data that reproduces $\hat{\theta}^*$

Shalizi, 2013

... indirect inference

Smith, 2008

- ▶ simulate samples y_t^m , m = 1, ..., M at some value θ
- ightharpoonup compute $\hat{ heta}^*(heta)$ from the simulated data

$$\hat{\theta}^*(\theta) = \arg\max_{\theta^*} \sum_{m} \sum_{t} \log f(y_t^m \mid y_{t-1}^m, x_t; \theta^*)$$

- choose θ so that $\hat{\theta}^*(\theta)$ is as close as possible to $\hat{\theta}^*$
- ▶ if p = d simply invert the 'bridge function'
- ▶ usually p > d
 - $\hat{\theta}_1 = \arg\min_{\theta} \{\hat{\theta}^*(\theta) \hat{\theta}\}^{\mathrm{T}} W \{\hat{\theta}^*(\theta) \hat{\theta}\}$
 - $\hat{\beta}_2 = \arg\min_{\theta} \left(\sum_t \log f(y_t \mid y_{t-1}, x_t, \hat{\theta}^*(\theta)) \sum_t \log f(y_t \mid y_{t-1}, x_t, \hat{\theta}) \right)$
- ightharpoonup estimates of θ are consistent, asymptotically normal, but not efficient

- simulate θ' from $\pi(\theta)$
- ▶ simulate data z from $f(\cdot; \theta')$
- ▶ if z = y then θ' is an observation from posterior $\pi(\cdot \mid y)$
- actually s(z) = s(y) for some set of statistics
- ▶ actually ρ {s(z), s(y)} < ϵ for some distance function ρ (·)

Fearnhead & Prangle, 2011

▶ many variations, using different MCMC methods to select candidate values θ'

... approximate Bayesian computation

M/G/1 queue: exponential arrival times, general service times, single server

observations y_i : times between departures from the queue unobserved variables V_i : arrival time of customer i

model:

- $V_1 \sim \text{Exp}(\theta_3)$
- $V_i \mid V_{i-1} \sim V_{i-1} + \text{Exp}(\theta_3)$
- Y_i | X_{i-1} , $V_i \sim \text{Uniform}\{\theta_1 + max(0, V_i X_{i-1}), \theta_2 + max(0, V_i X_{i-1})\}$ $X_i = \sum_{i=1}^i Y_i$
- service time $\sim U(\theta_1, \theta_2)$

ABC: use quantiles of departure times as summary statistics

Indirect Inference: use \bar{y} , $y_{(1)}$, $\hat{\theta}_2$ from steady-state model

Table 7. Mean quadratic losses for various analyses of 50 M/G/1 data sets†

Method	θ_1	θ_2	θ_3
Comparison Comparison + regression Semi-automatic ABC Semi-automatic predictors Indirect inference	1.1	2.2	0.0013
	0.020	1.1	0.0013
	0.022	1.0	0.0013
	0.024	1.2	0.0017
	0.18	0.42	0.0033

[†]Losses within 10% of the smallest values for that parameter are italicized.

- ▶ both methods need a set of parameter values from which to simulate: θ' or θ
- ▶ both methods need a set of auxiliary functions of the data s(y) or $\hat{\theta}^*(y)$
- in indirect inference, $\hat{\theta}^*$ is the 'bridge' to the parameters of real interest, θ
- C & K use orthogonal designs based on Hadamard matrices to chose θ'
- \blacktriangleright and calculate summary statistics focussed on individual components of θ
- MCMC estimation of log-likelihood function

cond. comp. likelihood poor for Ising model

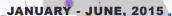
Geyer & Thompson, 1992 Okabayashi et al., 2011

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APRIL 13 - 17, 2015

Workshop on Big Data for Social Policy

This thematic program emphasizes both applied and theoretical aspects of statistical inference, learning and models in big data. The opening conference will serve as an introduction to the program, concentrating on overview lectures and background preparation. Workshops throughout the program will highlight cross-cutting themes, such as learning and visualization, as well as focus themes for applications in the social, physical and life sciences. It is expected that all activities will be webcast using the FieldsLive system to permit wide participation. Allied activities planned include workshops at PIMS in April and May and CRM in May and August.

ORGANIZING COMMITTEE

Yoshua Bengio (Montréal) Hugh Chipman (Acadia)

Sallie Keller (Virginia Tech)