

Statistical modelling for and with copulas

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Outline

Part I - Conditional Copulas

Motivation

Conceptualization

Estimation

Part II - Copulas in Statistical Models

Hidden Markov Models

Applications

Babies, Wine, Being there or not

Motivation - part 0

- ▶ The smoking cessation study of Liu, Daniels and Marcus (JASA '09):
 - Q = smoking cessation (0=No, 1=Yes)
 - W = weight change
 - X = time spent exercising
- ▶ Does exercise weaken the association between smoking status and weight gain?
- ▶ We are interested in understanding the covariate effect on the dependence pattern between responses.

Motivation - part 1

- ▶ Joint models for multivariate data.
- ▶ If the joint distribution of Y_1, Y_2, Y_3 ($Y_i \sim f_i, 1 \leq i \leq 3$) then

$$\begin{aligned} f(y_1, y_2, y_3) &= c_{12}(F_1(y_1), F_2(y_2))c_{23}(F_2(y_2), F_3(y_3)) \\ &\times c_{13|2}(F_{1|2}(y_1|y_2), F_{3|2}(y_3|y_2); y_2) f_1(y_1) f_2(y_2) f_3(y_3) \end{aligned}$$

- ▶ As dimension increases, the bivariate conditional copulas depend on increasing number of variables.
- ▶ Useful in prediction of one (expensive) response given the other (cheaper) ones.

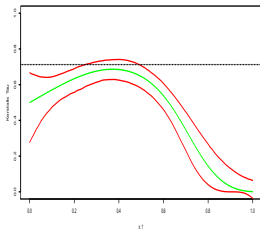
$$f(y_1|y_2, y_3) = c_{12}(F_1(y_1), F_2(y_2))c_{13|2}(F_{1|2}(y_1|y_2), F_{3|2}(y_3|y_2); y_2) f_1(y_1)$$

Motivation - part 2

- ▶ $Y_i|x \sim N(f_i(x), \sigma_i) \quad x \in \mathbb{R}^2$
- ▶ True marginal means:
 - ▶ $f_1(x) = 0.6 \sin(5x_1) - 0.9 \sin(2x_2)$
 - ▶ $f_2(x) = 0.6 \sin(3x_1 + 5x_2)$
 - ▶ $\sigma_1 = \sigma_2 = 0.2, \mathbf{X}_1 \perp \mathbf{X}_2.$
- ▶ Copula: $\tau(x) = 0.71$
- ▶ Suppose x_2 is not observed so inference is based only on x_1

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Motivation - part 2

- ▶ Simplified setting:

$$Y_i | X_1, X_2 \sim N(f_i(X_1, X_2), 1) \quad i = 1, 2$$

$$\text{Cor}(Y_1, Y_2 | X_1, X_2) = \rho$$

- ▶ Set $W_i = Y_i - E[Y_i | X_1]$ for $i = 1, 2$

$$\text{Cov}(W_1, W_2 | X_1) = \text{Cov}(Y_1, Y_2 | X_1), \quad (1)$$

and

$$\begin{aligned} \text{Cov}(Y_1, Y_2 | X_1) &= E_{X_2}[\text{Cov}(Y_1, Y_2 | X_1, X_2)] + \\ &+ \text{Cov}_{X_2}(E[Y_1 | X_1, X_2], E[Y_2 | X_1, X_2]) \\ &= \rho + \underbrace{\text{Cov}_{X_2}(f_1(X_1, X_2), f_2(X_1, X_2))}_{\text{constant in } X_1 \text{ if } f_i(X_1, X_2) = f_{i1}(X_1) + f_{i2}(X_2), i=1,2} \end{aligned}$$

- ▶ Omission of covariates \Rightarrow Non-constant calibration.

Conditional Copulas

- ▶ If $\mathbf{X} \in \mathbb{R}^d$ is a covariate

$$H(t_1, \dots, t_d | \mathbf{X}) = C_{\mathbf{X}}(F_1(t_1 | \mathbf{X}), \dots, F_d(t_d | \mathbf{X})).$$

- ▶ The **parametric CC** model assumes there is a family $\{C_{\theta} : \theta \in \Theta\}$ s.t.

$$C_{\mathbf{X}}(F_1(t_1 | \mathbf{X}), \dots, F_d(t_d | \mathbf{X})) = C_{\eta(\mathbf{X})}(F_1(t_1 | \mathbf{X}), \dots, F_d(t_d | \mathbf{X})).$$

- ▶ η is the **unknown calibration function** we are interested in.
- ▶ The **simplifying assumption (SA)**:

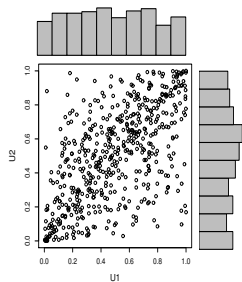
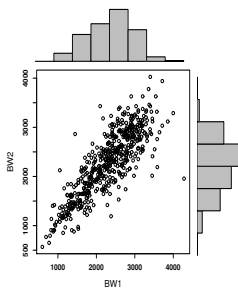
$$C_{\mathbf{X}}(F_1(t_1 | \mathbf{X}), \dots, F_d(t_d | \mathbf{X})) = C(F_1(t_1 | \mathbf{X}), \dots, F_d(t_d | \mathbf{X}))$$

or

$$\eta(\mathbf{X}) = \text{const.}$$

Semiparametric and Nonparametric

- ▶ Semiparametric and nonparametric methods (Acar, C. and Yao 2011; Veraverbeke, Omelka & Gijbels 2011)
- ▶ Estimate $\eta(X)$ after fitting the models for the marginals.
 - ▶ When marginals are unknown \rightarrow propagation of errors
 - ▶ Testing for $H_0 : \eta(x) = \text{const}$ is cumbersome and lacks power.
 - ▶ Scales poorly with dimension of X .



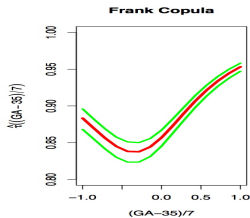
Bayesian Cubic Splines

- ▶ Joint Bayesian modelling of marginals and calibration regression models using cubic splines (C. & Sabeti 2012)
 - ▶ Suitable for $X \in \mathbb{R}$
 - ▶ Model comparisons between $M_0 : \eta(x) = \text{const}$ and $M_1 : \eta(x) \neq \text{const}$ favours M_1 .
- ▶ Use additive models when $X \in \mathbb{R}^d$ (Sabeti, Wang & C. 2014; Chavez-Demoulin & Vatter 2015)

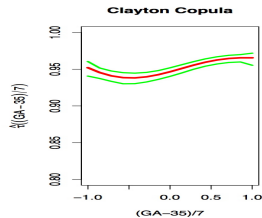
$$\eta(x_1, \dots, x_d) = \eta_0 + \sum_{i=1}^d \eta_i(x_i).$$

- ▶ Results are sensitive to violations of additivity.
- ▶ Additivity is not preserved when changing dependence measure.

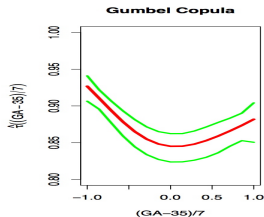
Twin Data Example



DIC=10449



DIC=14810



DIC=6.97 × 10⁷

GP Prior with Single Index Models

- ▶ When $X \in \mathbb{R}^d$ we consider the SIM model (Levi & C 2018)

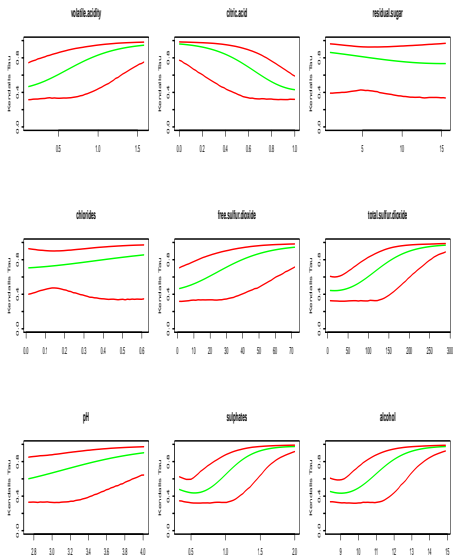
$$\eta(X) = f(\beta^T X). \text{ with } f : \mathbb{R} \rightarrow \mathbb{R} \text{ smooth.}$$

- ▶ f is estimated using a sparse Gaussian process prior
- ▶ This is **invariant to nonlinear one-to-one transformations** $\tau(\theta)$.
- ▶ Marginals are fitted also using GP-SIM models, but other models are possible.
- ▶ The parameter β is unidentifiable up to a constant so we assume $\|\beta\| = 1$.
- ▶ Allows for variable selection.

Red Wine

- ▶ 11 Physiochemical properties of 1599 varieties of red “Vinho Verde” Portuguese wine.
- ▶ We consider the dependence between **fixed acidity** and **density**. The former is strongly associated with quality of wine, while the latter is used as a measure of grape quality.
- ▶ Covariates: volatile acidity, citric acid, residual sugar, chlorides, free sulfur dioxide, total sulfur dioxide, pH, sulphates, alcohol.

Red Wine



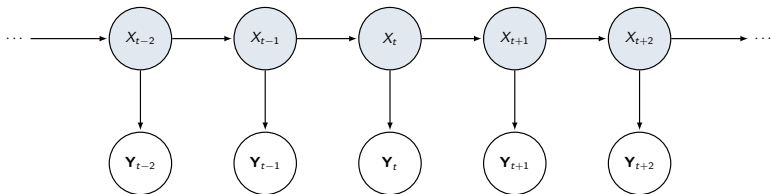
Part II: Copulas in Statistical Models

Based on "Copula Modelling of Serially Correlated Multivariate Data with Hidden Structures"

Co-authors: Robert Zimmerman and Vianey Leos-Barajas

Hidden Markov Models: A Primer

- ▶ A hidden Markov model (HMM) pairs an observed time series $\{\mathbf{Y}_t\}_{t \geq 1} \subseteq \mathbb{R}^d$ with a Markov chain $\{X_t\}_{t \geq 1}$ on some state space \mathcal{X} , such that the distribution of $\mathbf{Y}_s \mid X_s$ is independent of $\mathbf{Y}_t \mid X_t$ for $s \neq t$:



- ▶ $\mathbf{Y}_{t,h} \mid \{X_t = k\} \sim f_{k,h}(\cdot \mid \lambda_{k,h}) \quad \forall h = 1, \dots, d$
- ▶ $\{X_t\}$ is a Markov process (finite state space \mathcal{X}) with initial probability mass distribution $\{\pi_i\}_{i \in \mathcal{X}}$ and transition probabilities $\{\gamma_{i,j}\}_{i,j \in \mathcal{X}}$

Inferential aims for HMMs

- ▶ Typically, the chain $\{X_t\}_{t \geq 1}$ is partially or completely unobserved.
- ▶ The hidden states can correspond to a precise variable (occupancy data) or might be postulated (psychology, ecology, etc)
- ▶ **Aim 1:** Model the data generating mechanism [Nasri et al. \(2020\)](#)
- ▶ **Aim 2:** Decode (i.e., classify) or predict the X_t 's from the observed data.

Examples

- ▶ A tri-axial accelerometer captures a shark's acceleration with respect to three positional axes depending on the shark's activity (resting, hunting, attacking). For short periods some of the sharks are filmed.
- ▶ Stock exchanges keep track of real-time prices for hundreds of stocks within an industry, depending on market conditions/states (stagnant, growing, shrinking).
- ▶ In-game team statistics like shots on goal and ball touches in a soccer football match are changing with the “momentum” of the team (defensive, offensive, passive) [Ötting et al. \(2021\)](#)

Fusion of Multiple Data Sources

- ▶ In the real-world applications above, various sensors capture multiple streams of data, which are “fused” into a multivariate time series $\{\mathbf{Y}_t\}_{t \geq 1}$
- ▶ In such situations, the components of any $\mathbf{Y}_t = (Y_{t,1}, \dots, Y_{t,d})$ cannot be assumed independent (even conditional on X_t)
- ▶ The corresponding assumption for HMMs – that of contemporaneous conditional independence [Zucchini et al. \(2017\)](#) – is often violated
- ▶ Instead, it is common to assume that \mathbf{Y}_t follows a multivariate Gaussian distribution, but this places limits on marginals and dependence structures
- ▶ What if the strength of dependence – or even the “kind” of dependence – between the components of \mathbf{Y}_t could be informative about the underlying state X_t ?

Copulas Within HMMs

- ▶ Our model consists of an HMM $\{(\mathbf{Y}_t, X_t)\}_{t \geq 1} \subseteq \mathbb{R}^d \times \mathcal{X}$ in which the state-dependent distributions are copulas:

$$\mathbf{Y}_t \mid (X_t = k) \sim H_k(\cdot) = \underbrace{C_k\left(F_{k,1}(\cdot; \lambda_{k,1}), \dots, F_{k,d}(\cdot; \lambda_{k,d})\right)}_{\text{depends on the hidden state value } k} \mid \theta_k.$$

- ▶ $C_k(\cdot, \dots, \cdot \mid \theta_k)$ is a d -dimensional parametric copula
- ▶ $\{X_t\}_{t \geq 1}$ is a Markov process on finite state space $\mathcal{X} = \{1, 2, \dots, K\}$ and K is known
- ▶ In this model, virtually all aspects of the state-dependent distributions are allowed to vary between states

Information in the dependence

- ▶ For a range of $\theta \in [0, 100)$, we simulated a bivariate time series of length $T = 100$ from the 2-state HMM

$$\mathbf{Y}_t \mid (X_t = k) \sim C_{\text{Frank}}(\mathcal{N}(0, 1), \mathcal{N}(0, 1) \mid (-1)^k \cdot |\theta|), \quad k = 1, 2$$

and then separately assessed the accuracy of a standard decoding algorithm, first assuming independent margins and then the true model:

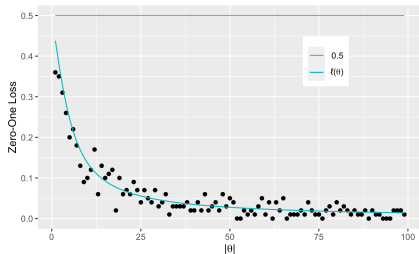


Figure: Zero-one losses for independent margins (red dots) and true model (blue dots)

Stronger Dependence Leads to Better Accuracy

- ▶ In fact, $\ell_{01}(\theta) = \frac{1}{2} - \frac{2}{\theta} \log(\cosh \frac{\theta}{4}) \rightarrow 0$ as $\theta \rightarrow \infty$
- ▶ Similar formulas hold for other radially symmetric copulas
- ▶ Much more generally, we have the following:

Theorem

Let $\nu_{t,k} = \mathbb{P}(X_t = k)$. The expected zero-one loss of the classifications made by local decoding is given by

$$\ell_{01}(\boldsymbol{\eta}) = 1 - \frac{1}{T} \sum_{t=1}^T \sum_{k=1}^K \nu_{t,k} \int_{\mathbb{R}^d} \mathbb{1} \left\{ \frac{\nu_{t,k} \cdot h_k(\mathbf{y})}{\max_{j \neq k} \nu_{t,j} \cdot h_j(\mathbf{y})} > 1 \right\} dH_k(\mathbf{y}).$$

where $h_k(\mathbf{Y})$ is the joint density of $\mathbf{Y}|X = k$.

- ▶ Corollary: as the copula in any particular state approaches either of the Fréchet-Hoeffding bounds, the observations produced by that state will be detected with complete accuracy

Estimation with missing data

- ▶ Data consist in observed $\mathbf{Y}_{1:T}$ and missing $X_{1:T}$
- ▶ Parameters are $\eta = \{\lambda_{h,k}\}_{\substack{h=1:d \\ k=1:T}} \cup \{\theta_k\}_{k=1:T} \cup \{\gamma_{i,j}\}_{\substack{i=1:K \\ j=1:K}} \cup \{\pi_j\}_{j=1:K}$.
- ▶ The complete-data log-likelihood for one trajectory of the copula HMM is given by

$$\begin{aligned} \ell_{\text{com}}(\boldsymbol{\eta} \mid \mathbf{y}_{1:T}, X_{1:T}) &= \pi_{X_1} + \sum_{t=2}^T \log \gamma_{X_{t-1}, X_t} + \sum_{h=1}^d \log f_{X_t, h}(y_{t, h}; \lambda_{X_t, h}) \\ &+ \sum_{t=1}^T \log c_{X_t}(F_{X_t, 1}(y_{t, 1}; \lambda_{X_t, 1}), \dots, F_{X_t, 1}(y_{t, d}; \lambda_{X_t, d}) \mid \theta_{X_t}). \end{aligned} \quad (2)$$

Inference for HMMs Via the EM Algorithm

- ▶ Without copula, the estimation is done via the EM algorithm (aka Baum-Welch)

E-step Compute $Q(\eta|\eta^{(s)}) = E[l_{com}(\eta|\mathbf{Y}_{1:T}, X_{1:T})|\eta^{(s)}, \mathbf{Y}_{1:T}]$

M-step Set $\eta^{(s+1)} = \arg \max_{\eta} Q(\eta|\eta^{(s)})$

- ▶ The complete-data log-likelihood is written in terms of the state membership indicators $U_{k,t} = \mathbb{1}_{X_t=k}$ and $V_{j,k,t} = \mathbb{1}_{X_{t-1}=j, X_t=k}$
- ▶ In the **E-Step**, these indicators are estimated by the conditional probabilities $\hat{u}_{k,t} = \mathbb{P}(X_t = k | \mathbf{Y}_{1:T} = \mathbf{y}_{1:T})$ and $\hat{v}_{j,k,t} = \mathbb{P}(X_{t-1} = j, X_t = k | \mathbf{Y}_{1:T} = \mathbf{y}_{1:T})$, which are computed based on current parameter estimates
- ▶ This only requires evaluating the state-dependent densities at each of the observations $\mathbf{y}_1, \dots, \mathbf{y}_T$ (this is “OK”)

The M-Step Is Hard

- ▶ In the **M-Step**, the resulting complete-data log-likelihood is maximized with respect to all parameters in the model simultaneously
 - ▶ Only for the simplest univariate models do the state-dependent MLEs exist in closed form; otherwise, one must resort to numerical methods (**this is hard!**)
 - ▶ Evaluating a copula density $c_k(\cdot, \dots, \cdot \mid \theta_k)$ in high dimensions is slow
 - ▶ When the state-dependent distributions in an HMM are copulas, performing the M-Step directly requires the evaluation of

$$\operatorname{argmax}_{\{\theta_k\}, \{\lambda_{k,h}\}} \left\{ \sum_{k=1}^K \sum_{t=1}^T \hat{u}_{k,t} \left[\log c_k \left(F_{k,1}(y_{t,1}; \lambda_{k,1}), \dots, F_{k,d}(y_{t,d}; \lambda_{k,d}) \mid \theta_k \right) + \sum_{h=1}^d \log f_{k,h}(y_{t,h}; \lambda_{k,h}) \right] \right\}$$

- ▶ This is very unstable (and slow)

Inference Functions for Margins

- ▶ Likelihood-based inference for copulas is easier when the goal is to estimate θ alone in the presence of known margins
- ▶ Why not perform inference on the marginal distributions first, and then on the copula itself?
- ▶ In the context of iid data, this is exactly the inference functions for margins (IFM) approach of [Joe and Xu \(1996\)](#):
 - ▶ First estimate each λ_h by its “marginal MLE” $\hat{\lambda}_h$ given $\{Y_{t,h}\}_{t \geq 1}$, for $h \in \{1, \dots, d\}$
 - ▶ Then estimate θ assuming fixed marginals $F_1(\cdot; \hat{\lambda}_1), \dots, F_d(\cdot; \hat{\lambda}_d)$
- ▶ One can show that the IFM estimator is consistent and asymptotically normal (although relatively less efficient than the MLE)

A Better Approach

- ▶ Replace the M-Step in the EM algorithm with an IFM iteration to create an “EFM algorithm”
- ▶ For $T \in \{100, 1000, 5000\}$ and $d \in \{2, 5, 10\}$, we simulated a d -dimensional time series of length T from the 2-state HMM

$$\mathbf{Y}_t \mid (X_t = 1) \sim C_{\text{Frank}} \left((\mathcal{N}(\mu_{1,h} = -h, 1))_{h=1}^d \mid \theta_1 = 3 \right)$$

$$\mathbf{Y}_t \mid (X_t = 2) \sim C_{\text{Clayton}} \left((\mathcal{N}(\mu_{2,h} = h, 1))_{h=1}^d \mid \theta_2 = 3 \right)$$

and estimated $\boldsymbol{\eta} = (\mu_{1,1}, \dots, \mu_{2,d}, \theta_1, \theta_2)$ using both approaches

- ▶ Applied to the basic EM algorithm, R's `optim` with L-BFGS-B (i.e., quasi-Newton with box constraints) typically fails as soon as $d \geq 3$
 - ▶ The procedure is extremely sensitive to initial values and requires $\hat{\boldsymbol{\eta}}^{(0)} \approx \boldsymbol{\eta}$ just to avoid overflow
 - ▶ This kind of tuning is very tedious or impossible in high dimensions

Does This Work?

- ▶ We keep track of the **time** (in seconds) until the algorithm converges, and the **L_2 error** of the resulting estimate, $\epsilon = \|\boldsymbol{\eta} - \hat{\boldsymbol{\eta}}\|_2$
 - ▶ We used the `lbfgsb3c` package, which is more stable than `optim`

	$d = 2$	$d = 5$	$d = 10$
$T = 100$	111.9 s, $\epsilon = 0.14$	123.4 s, $\epsilon = 299.98$	111.8 s, $\epsilon > 10^9$
$T = 1000$	166.6 s, $\epsilon = 0.63$	169.5 s, $\epsilon > 10^{11}$	418.23 s, $\epsilon = 725.06$
$T = 5000$?	?	?

Table: EM Algorithm

	$d = 2$	$d = 5$	$d = 10$
$T = 100$	5.1 s, $\epsilon = 2.9$	3.0 s, $\epsilon = 0.94$	4.2 s, $\epsilon = 0.58$
$T = 1000$	34.4 s, $\epsilon = 0.57$	22.9 s, $\epsilon = 0.60$	34.4 s, $\epsilon = 0.80$
$T = 5000$	172.6 s, $\epsilon = 0.13$	106.2 s, $\epsilon = 0.12$	168.7 s, $\epsilon = 0.19$

Table: EFM Algorithm

This Works

- ▶ R has no problem with the EFM algorithm
- ▶ The algorithm is considerably less sensitive to starting values than the vanilla EM algorithm, and terminates much faster
- ▶ It is also theoretically justified
 - ▶ We show that the sequence of estimates produced by our algorithm will converge, and the resulting estimator is consistent and asymptotically normal (under mild regularity conditions)
 - ▶ Accomplished by viewing our method as an adaptation of the ES algorithm of [Elashoff and Ryan \(2004\)](#) and using established asymptotic theory of M-estimators for HMMs [Jensen \(2011\)](#)

Occupancy Data

- ▶ The ability to detect whether a room is occupied using sensor data (such as temperature and CO_2 levels) can potentially reduce unnecessary energy consumption by automatically controlling HVAC and lighting systems, without the need for motion detectors
- ▶ Consider three publicly-available labelled datasets presented by [Candanedo and Feldheim \(2016\)](#) which contain multivariate time series of four environmental measurements (light, temperature, humidity, CO_2) and one derived metric (the humidity ratio)
- ▶ Data contain binary indicators for whether the room was occupied or not at the time of measurement

Occupancy Data

- ▶ Several common families of parametric copulas (the Frank, Clayton, Gumbel, Joe, and Gauss families), and for each we carried out a goodness-of-fit test based on the pseudo-observations using the multiplier bootstrap method ([Kojadinovic et al., 2011](#))
- ▶ The parametric family based on the lowest corresponding Cramér-von Mises test statistic is selected.
- ▶ This process yielded a Clayton copula for State 1 and a Frank copula for State 2

State	Frank	Clayton	Gumbel	Joe	Gauss
1	0.356	0.255	0.423	0.770	0.345
2	0.018	0.433	0.038	0.206	0.045

Table: Cramér-von Mises test statistics based on pseudo-observations computed from unoccupied (Row 1) and occupied (Row 2) subsets.

Occupancy Data

- Denote the unoccupied state as '1' and the occupied state as '2'

$$\mathbf{Y}_t \mid (X_t = 1) \sim C_{\text{Clayton}}(\mathcal{N}(\mu_{1,1}, \sigma_{1,1}^2), \mathcal{N}(\mu_{1,2}, \sigma_{1,2}^2) \mid \theta_1)$$

$$\mathbf{Y}_t \mid (X_t = 2) \sim C_{\text{Frank}}(\mathcal{N}(\mu_{2,1}, \sigma_{2,1}^2), \mathcal{N}(\mu_{2,2}, \sigma_{2,2}^2) \mid \theta_2).$$

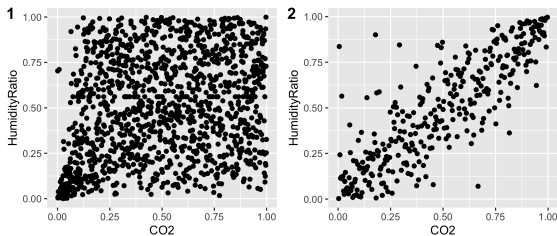


Figure: Pseudo-observations computed from unoccupied (Panel 1) and occupied (Panel 2) subsets.

Occupancy Data

Copula Model	Train	Test 1	Test 2
Independence	0.895	0.846	0.680
Clayton/Frank	0.899	0.852	0.696

Table: Overall state classification accuracy for the training dataset and the two test datasets using either the independence or Clayton/Frank copula.

Discussion

- ▶ Copulas are interesting objects that can play useful roles in statistical models
- ▶ Allow data fusion in many contexts
- ▶ Customized computation is often required
- ▶ Future: computation and model selection for/with vine copulas

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My own papers are available on my homepage: <http://www.utstat.toronto.edu/craiu/>